

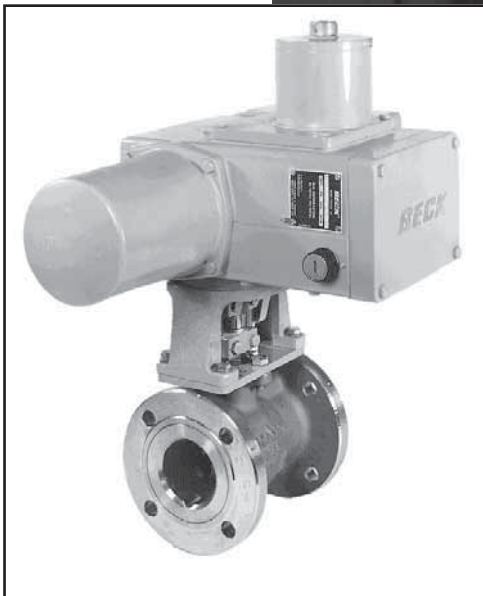
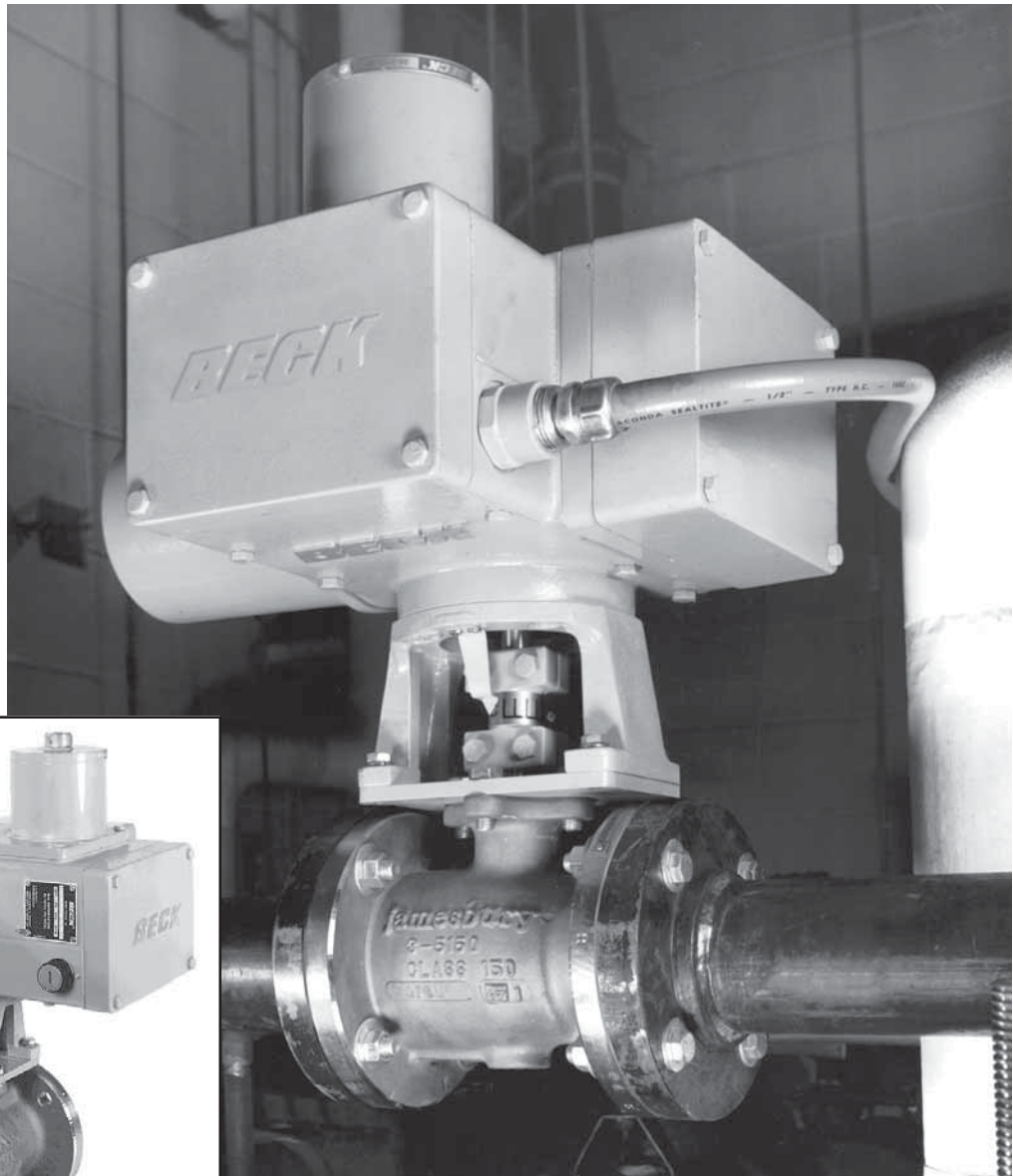
80-1101-01
Rev. 09.1

MODELS 11-16_
11-26_
11-36_
11-46_

BECK®

INSTRUCTION MANUAL

For drives built after
September 1999 with
CW/CCW Handswitch



ELECTRIC ACTUATORS FOR INDUSTRIAL PROCESS CONTROL

INTRODUCTION TO THE MANUAL

This manual contains the information needed to install, operate and maintain the Beck 11-160, 11-260, 11-360 and 11-460 Electronic Control Drives, manufactured by Harold Beck & Sons, Inc. of Newtown, Pennsylvania.

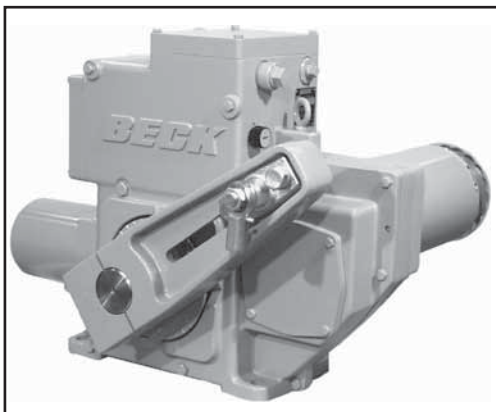
The Group 11 drive is a powerful control package designed to provide modulating control of quarter-turn valves requiring up to 1,800 lb-ft (2 440 N•m) of drive torque.

IMPORTANT: This manual contains information that will make installation simple, efficient and trouble-free. Please read and understand the appropriate sections in this manual before attempting to install or operate your drive.

This manual also applies to Group 11 & 11E hazardous location drives and, with such orders, is provided along with Beck Manual Supplement 80-1100-14.



Group 11 quarter-turn drives and valve/drive assemblies provide precise, reliable control of ball, plug and butterfly valves. All drives are delivered fully calibrated to the specifications written into the equipment order and are ready for installation.



Group 11 rotary drives ... provide precise position control of dampers, valves, fluid couplings, and other devices requiring up to 1,800 lb-ft drive torque.



Group 14 linear drives ... are ideally suited for globe valves from 1" to 8" diameter. Beck's unique "Tight-Seater™" coupling provides positive seating of valves.



Group 31 rotary drives ... are particularly suited for coupling to ball, plug, and butterfly valves up to 4" diameter, and small dampers.

CONTENTS

PRODUCT SUMMARY

Beck control drives are engineered for precise, reliable operation of quarter-turn valves. The cool, stable operation of Beck's control motors coupled with the powerful gear train provide the tight, responsive control required by modern control loops to optimize output while keeping operating costs low.

The unique, all spur gear construction used in the Beck control drive is designed for long term durability. The gear train can withstand accidental stalls of up to four days without failure, and will resume instant response immediately upon removal of the condition (see page 22 for Stall Protection and Annunciation information). Gear modules and motors can be interchanged in the field to alter the torque and timing as needed if the application requirements change. Mechanical stops in the gear train prevent over-travel.

An easy-to-turn, spoke-free Handwheel is incorporated into the design to allow manual operation during installation or power outages. The Handwheel can be used to move valves to any position smoothly and easily under full load conditions.

Valves may also be operated at their individual locations with built-in electric Handswitches.

Beck's ESR-4 Electronic Signal Receiver provides precise drive control from either conventional analog or computer based control systems.

Beck's CPS-2 Contactless Position Sensor provides accurate position feedback in demanding environmental conditions, with no contacting or wiping surfaces to wear or intermittently lose contact. The CPS-2 provides infinite resolution with linearity error of less than $\pm 1\%$ of span over full control drive travel.

Beck electronic control drives are designed with individual weatherproof enclosures to protect the main components.

TYPICAL APPLICATIONS

Group 11 units are engineered for direct coupling on quarter-turn ball, plug, and butterfly valves. Drives can be supplied assembled to valves for in-line installation or with hardware for mounting to existing valves.

Used in thousands of modulating valve applications, Beck drives have a field-proven track record for 100% availability and tight, reliable closure.

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PRODUCT DESCRIPTION

GENERAL SPECIFICATIONS—ALL MODELS

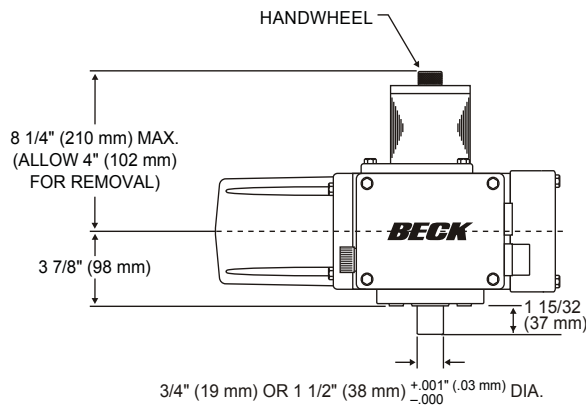
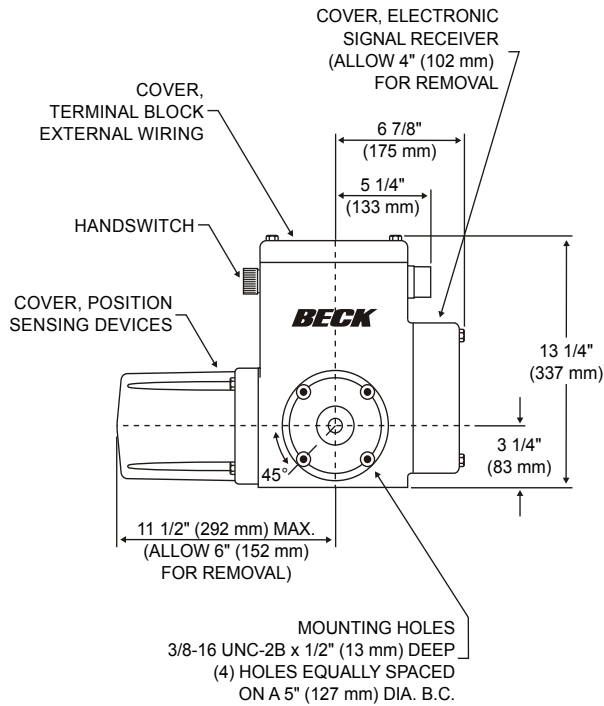
Input Power	120 V ac single-phase 50 or 60 Hz 240 V ac single-phase 50 or 60 Hz	Allowable Tolerance	+10% -15%
Model	Max. Current and Power		
	120 V ac	240 V ac	
11-160	.40 A 48 W	.20 A	48 W
11-260	.65 A 78 W	.33 A	78 W
11-360	.65 A 78 W	.33 A	78 W
11-460	3.10 A 400 W	1.55 A	400 W
Operating Conditions	-40° to 185°F (-40° to 85°C) 0 to 99% relative humidity		
Input Signal Options, with Electronic Signal Receiver (ESR-4)	0–5 mA 1–5 mA 4–20 mA 10–50 mA 1–5 V dc -10 to 10 V dc		
Input Signal Span Adj.	50% to 400% of span (except -10 to 10 V dc)		
Input Signal Zero Adj.	-100% to +275% of span (except -10 to 10 V dc)		
Deadband	0.6% of span (recommended deadband for most applications). Narrower and wider deadbands are available.		
Sensitivity	25% of deadband		
Direct AC Control	120 V ac for 2-position, multi-position or modulating V ac control		
Square Function (Optional)	Drive output shaft moves proportionally to the square of the input signal.		
Feedback Signal Options, with Contactless Position Sensor (CPS-2)	1–5 mA 4–20 mA 10–50 mA 1–5 V dc 0–16 V dc -10 to +10 V dc		
Output Stability	0.25% of span from 102 to 132 V ac ±0.03% of span/°C for 0 to 50°C, ±0.05% of span/°C for -40° to 85°C		
Linearity	±1% of span, max. independent error		
Hysteresis	0.25% of span at any point		
Isolation	Max. leakage of 10 µA at 60 V rms, 60 Hz from output to ground		

GENERAL SPECIFICATIONS—ALL MODELS (cont'd)

Film Potentiometer	1,000 ohms
Max. Voltage	40 V
Wattage	2 W max.
Linearity	±0.5%
Max. Wiper Current	1 mA
Action on Loss of Power	Stays in place
Action on Loss of Input Signal (Power On)	Stays in place or moves to full travel or zero position. Drives to any preset position with optional switch assembly on Models 11-__7 and 11-__8. Field adjustable.
Stall Protection and Annunciation (Optional)	If the motor tries to run in one direction for more than 300 seconds, the Stall Protection Module will shut off power to the motor and a solid state relay will change state. The relay is rated for 120 V ac or dc, 10 VA.
Limit Switches	Two SPDT, one for CW and one for CCW limit of travel. Standard switch setting is for 90° of travel.
Auxiliary Switches	Up to four 6 A, 120 V ac switches available. Switches are labeled S1 to S4 and are cam-operated, field-adjustable. S1 and S4 are set to operate just before reaching the CCW travel limit. S2 and S3 are set to operate just before reaching the CW travel limit.
Handswitch	Permits local electrical operation, independent of controller signal. Standard on all units.
Handwheel	Provides manual operation without electrical power.
Motor	120 V ac, single-phase, no-burnout, non-coasting motor has instant magnetic braking. Requires no contacts or moving parts. Can remain stalled for approximately 4 days (cumulative) without damaging the gear train.
Gear Train	High-efficiency, precision-cut, heat-treated alloy steel and ductile iron spur gears. Interchangeable gear modules permit field change of timing.
Mechanical Stops	Prevent overtravel during automatic or manual operation.
Enclosure	Precision-machined aluminum alloy castings, painted with corrosion-resistant polyurethane paint, provide a rugged, dust-tight, weatherproof enclosure. NEMA 4X; IP68, 3 meters/48 hours*. *Internal water damage is not covered by warranty.
Standards*	UL listed, CSA listed, CE compliant
*Note: For specific standards, please call Beck for more information at 215-968-4600.	

PRODUCT DESCRIPTION

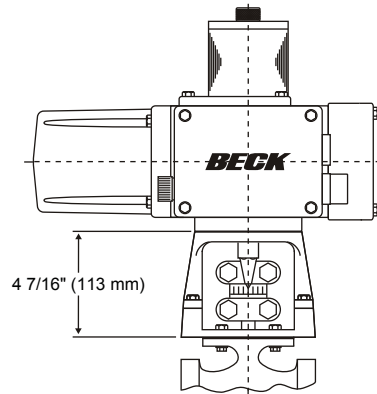
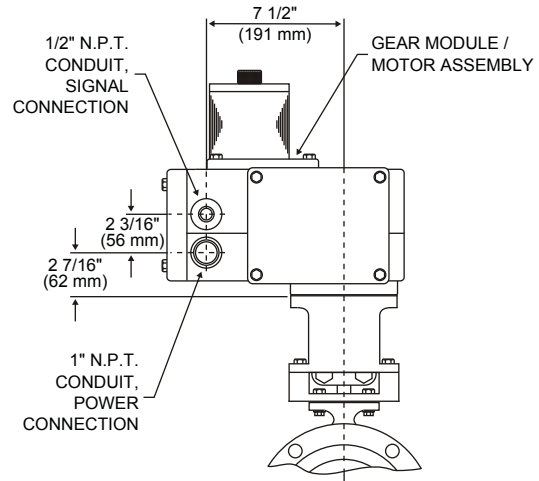
MODEL 11-160 SPECIFICATIONS



BASIC CONTROL DRIVE

Model Information

Approximate Weight	56 lbs. (25 kg)
Maximum Overhung Load	750 lbs. (340 kg)



TYPICAL VALVE MOUNTING

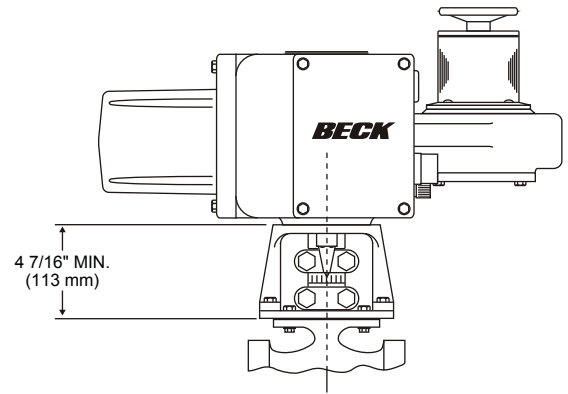
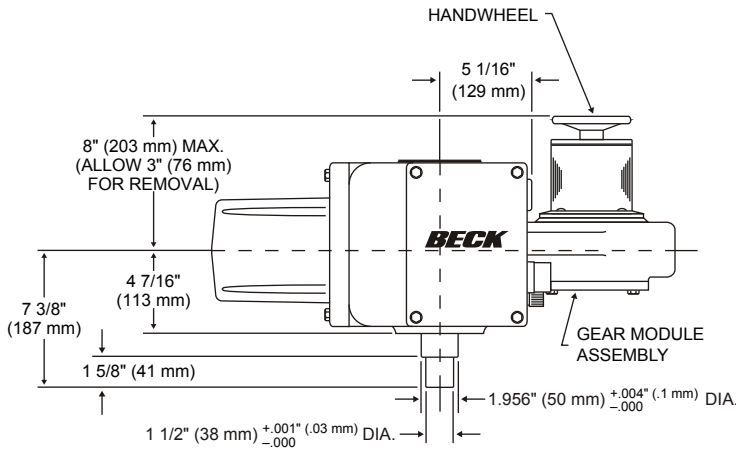
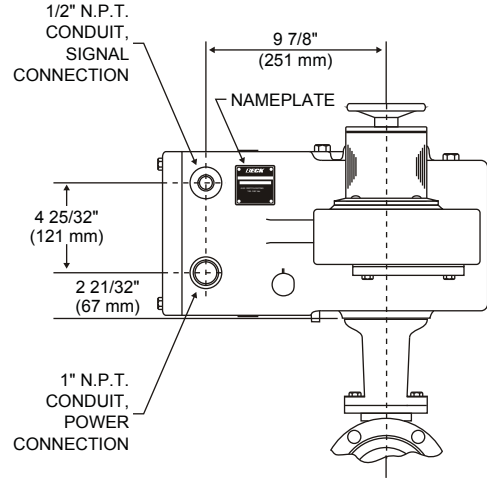
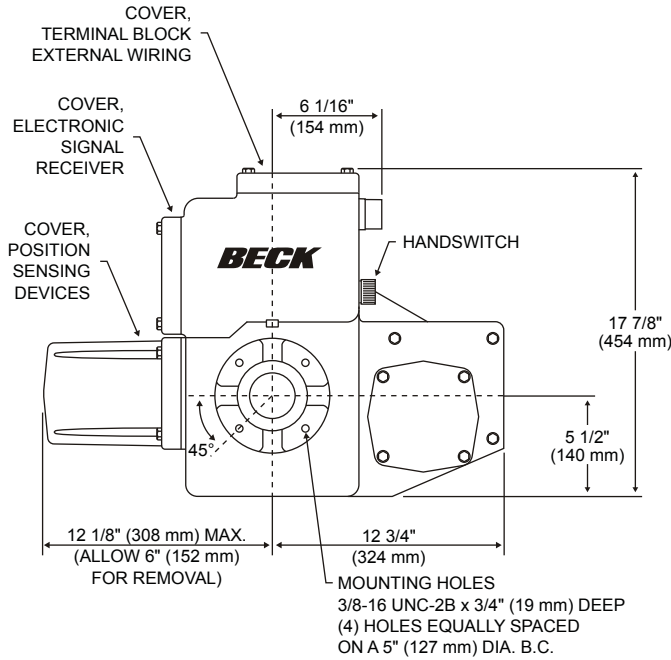
Recommended Bolt Torques

	Size (in.)	Torque	
		(lb-ft)	(N•m)
Cover Bolts	5/16-18	10	14
Motor/Gear Module Bolts	1/4-20	6	8
Body Bolts	5/16-18	10	14
Body Bolts	3/8-16	20	27
Control End Cover Bolts	5/16-18	10	14
Coupling Bolts	3/8-24	50*	68*
Mounting Bracket Screws (Flat Head)	3/8-16	25	34

*May vary per application. Refer to valve mounting specification sheet shipped with your drive.

NOTE: All dimensions subject to change.

MODEL 11-260 SPECIFICATIONS



TYPICAL VALVE MOUNTING

BASIC CONTROL DRIVE

Model Information

Approximate Weight	115 lbs. (52 kg)
Maximum Overhung Load	3,000 lbs. (1 361 kg)

Recommended Bolt Torques

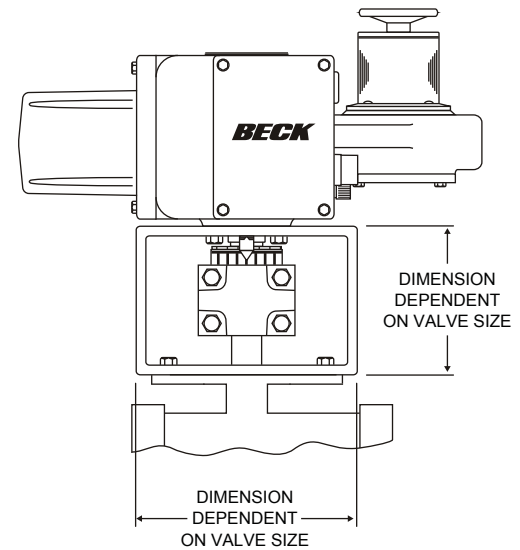
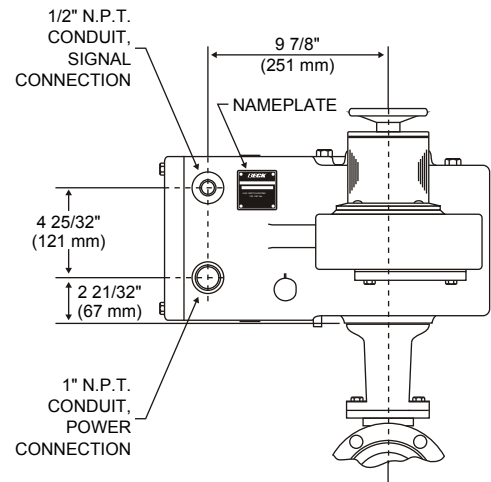
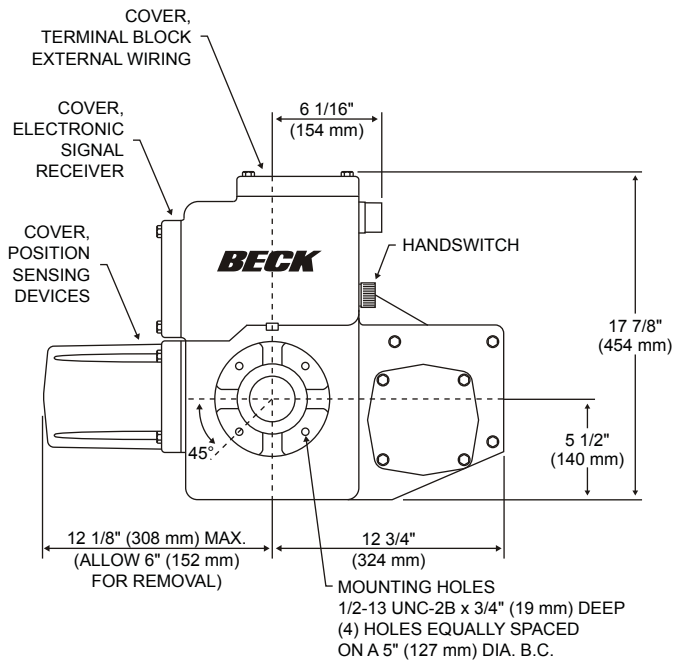
	Size (in.)	Torque	
		(lb-ft)	(N•m)
Cover Bolts	5/16-18	10	14
Gear Module Bolts	5/16-18	10	14
Motor Bolts	1/4-20	6	8
Body Bolts	3/8-16	20	27
Body Bolts	1/2-13	50	68
Control End Cover Bolts	5/16-18	10	14
Coupling Bolts	5/8-18	170*	230*
Mounting Bracket Screws (Flat Head)	3/8-16	25	34

*May vary per application. Refer to valve mounting specification sheet shipped with your drive.

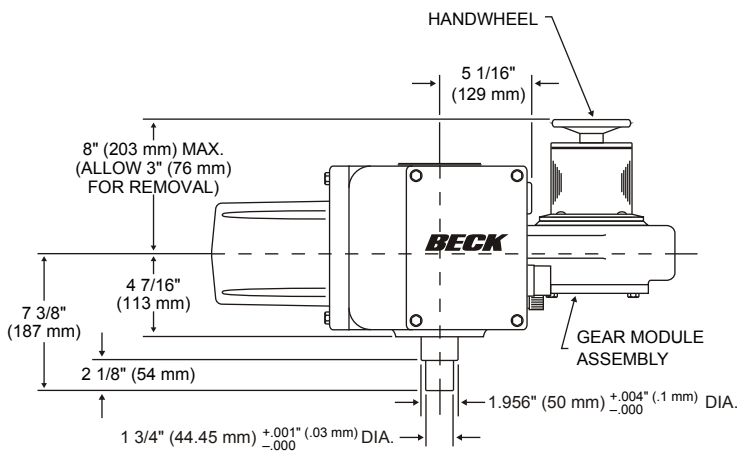
NOTE: All dimensions subject to change.

PRODUCT DESCRIPTION

MODEL 11-360 SPECIFICATIONS



TYPICAL VALVE MOUNTING



BASIC CONTROL DRIVE

Model Information

Approximate Weight	115 lbs. (52 kg)
Maximum Overhung Load	4,500 lbs. (2 041 kg)

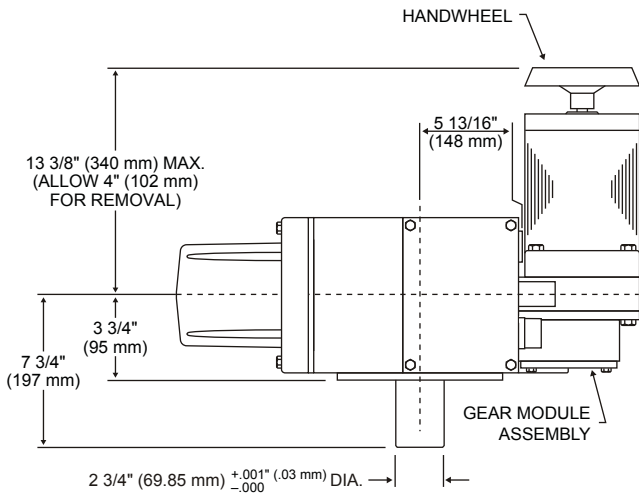
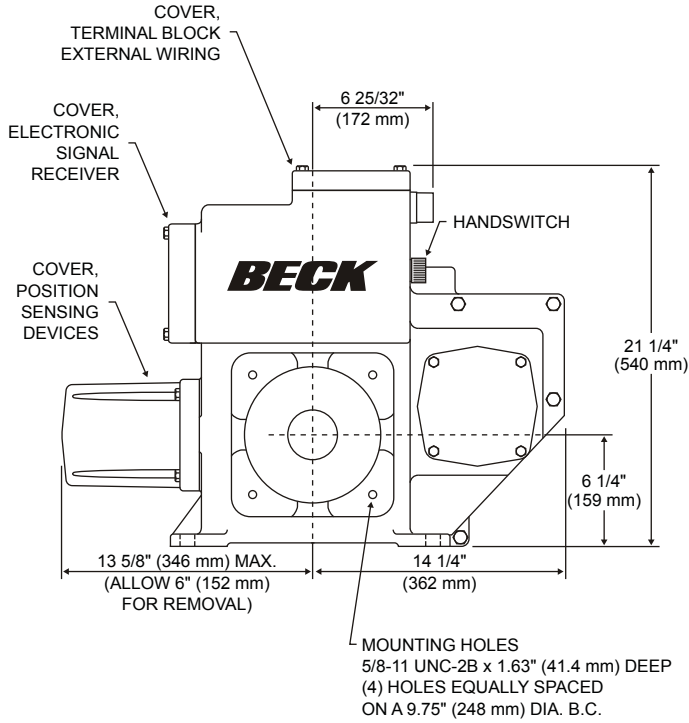
Recommended Bolt Torques

	Size (in.)	Torque	
		(lb-ft)	(N•m)
Cover Bolts	5/16-18	10	14
Gear Module Bolts	5/16-18	10	14
Motor Bolts	1/4-20	6	8
Body Bolts	3/8-16	20	27
Body Bolts	1/2-13	50	68
Control End Cover Bolts	5/16-18	10	14
Coupling Bolts	5/8-18	170*	230*
Mounting Bracket Screws	1/2-13	50	68

NOTE: All dimensions subject to change.

*May vary per application. Refer to valve mounting specification sheet shipped with your drive.

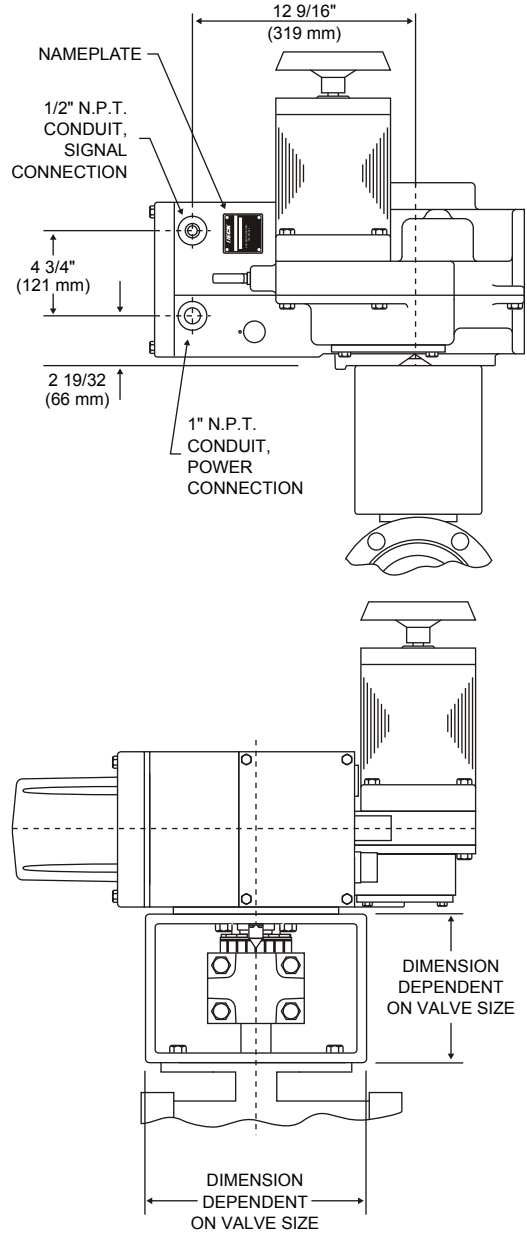
MODEL 11-460 SPECIFICATIONS



BASIC CONTROL DRIVE

Model Information

Approximate Weight	216 lbs. (98 kg)
Maximum Overhung Load	9,000 lbs. (4 082 kg)



TYPICAL VALVE MOUNTING

Recommended Bolt Torques

	Size (in.)	Torque	
		(lb-ft)	(N•m)
Cover Bolts	5/16-18	10	14
Gear Module Bolts	5/16-18	10	14
Motor Bolts	3/8-16	16	22
Body Bolts	3/8-16	20	27
Body Bolts	1/2-13	50	68
Control End Cover Bolts	5/16-18	10	14
Coupling Bolts	5/8-18	170*	230*
Mounting Bracket Bolts	5/8-11	100	135

*May vary per application. Refer to valve mounting specification sheet shipped with your drive.

NOTE: All dimensions subject to change.

PRODUCT DESCRIPTION

**TABLE 1:
SUMMARY OF CONTROL OPTIONS**

MODEL NUMBER	CONTROL TYPE	INPUT SIGNAL	ESR-4 BOARD NO.	INTEGRAL FEEDBACK DEVICE	EXTERNAL OUTPUT SIGNAL	CPS-2 PART NO. W/O MONITOR	CPS-2 PART NO. W/ MONITOR	AUXILIARY SWITCH OPTIONS		
11-__8	Electronic Modulating	0-5 or 1-5 mA dc	13-2245-02	CPS-2 Contactless Position Sensor	1-5 V dc or 4-20 mA	N / A	20-3400-12	None 2 4 2+INTLOS		
			13-2245-03*		16 V dc or 50 mA max.		20-3400-13			
		10-50 mA dc			0-15 V dc		20-3400-14			
			-10 to 10 V dc		20-3400-15					
11-__7		1-5 V dc	13-2245-04	1000 ohm Potentiometer 20-3060-03	None 1000 ohm Aux. Pot.		None 1000 ohm Aux. Pot.	N / A	None 2 4 2+INTLOS	
			13-2245-05							
			13-2245-08							
11-__6		Direct AC Control (Modulating)	120 V ac	None	CPS-2 Contactless Position Sensor		1-5 V dc or 4-20 mA	N / A	20-3400-02	None 2 4
	Low Power 120 V ac			13-2245-50 (Relay Board)		16 V dc or 50 mA max.	20-3400-03			
			Low Power dc	13-2245-51 (Relay Board)		0-15 V dc	20-3400-04			
	-10 to 10 V dc			20-3400-05						
11-__5	120 V ac		None	None	None 1000 ohm Aux. Pot.	None 1000 ohm Aux. Pot.	N / A		None 2 4	
			Low Power 120 V ac							13-2245-50 (Relay Board)
			Low Power dc							13-2245-51 (Relay Board)
11-__4	6 Position		120 V ac	N / A	None	None	N / A		None	
	5 Position									
	3 Position									
2 Position Open / Close										
11-__3	2 Position Open / Close							None 2 4		

*13-2245-09 Square Function board is available in these ranges.

INSTALLATION

SAFETY PRECAUTIONS

WARNING

Installation and service instructions are for use by qualified personnel only. To avoid injury and electric shock, do not perform any servicing other than that contained in this manual.

STORAGE INFORMATION

The drive should be stored in its shipping carton in a clean, dry area.

If it is necessary to store the drive outdoors for a long period of time, it should be removed from its shipping carton and stored above ground. A waterproof cover should be securely fastened over it. Do not stack drives on top of one another. Stored drives should be periodically checked to make sure no condensation has formed in the control compartments. Damage due to moisture while in storage is not covered by warranty.

UNPACKING

Beck drives are packed in standardized cardboard shipping containers. Drives mounted on valves are strapped to a skid and crated. After unpacking, the wooden platform may be used to transport the drive to the installation site.

INSTALLATION—ELECTRICAL

NOTE: All Beck drives are shipped from the factory ready for installation; no electrical adjustments are required before placing them in operation. Each drive is set up and calibrated to the customer's specifications that were written into the equipment order.

Two N.P.T. conduit connections are provided for power and signal wiring to the drive. The 1/2" conduit is provided for signal wiring connections, and the 1" conduit is provided for power and auxiliary switch connections. A sealant must be used on threaded conduit connections to keep moisture out. Conduits should be routed from below the drive so that condensation and other contaminants entering the conduit cannot enter the drive.

A large, clearly labeled terminal block on the top of the drive is enclosed in a separate, gasketed metal enclosure. Terminals will accommodate up to 12 AWG (3.31 mm²) wiring. See pages 6–9 for location of the terminal block.

CAUTION

Always close covers immediately after installation or service to prevent moisture or other foreign matter from entering the drive.

Refer to the wiring diagram furnished with your Beck drive for proper AC power and signal connections. It is advisable to provide normal short circuit protection on the AC power line. A copy of the wiring diagram is shipped with each drive and is fastened to the inside of the terminal block cover. If there is no wiring diagram available, you may obtain a copy from Beck by providing the serial number of your drive.

Your Beck drive has been supplied to match the signal source in your control loop. If it does not match, refer to the Input Signal Options section of this manual, page 16, for information on how to change the input signal range.

For maximum safety, the Beck drive body should be grounded. Use the grounding terminal in the wiring compartment of the drive.

INSTALLATION *INPUT SIGNAL WIRING*

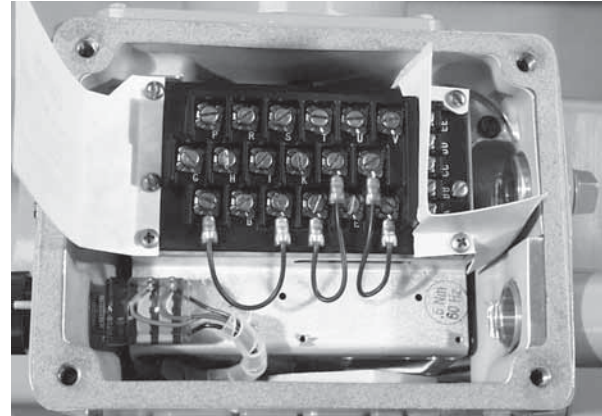
Each Beck drive is custom built with one of six separate control configurations provided to match the control requirements of your system. Basic wiring connections for each control option are described in the following paragraphs and diagrams.

The wiring diagram specific to each drive is attached to the inside of the wiring terminal cover. See Table 1, page 10, for model numbers and control selections.

Feedback connections for drives incorporating the Contactless Position Sensor (CPS-2) for control options 6 and 8 are described on pages 14–15.

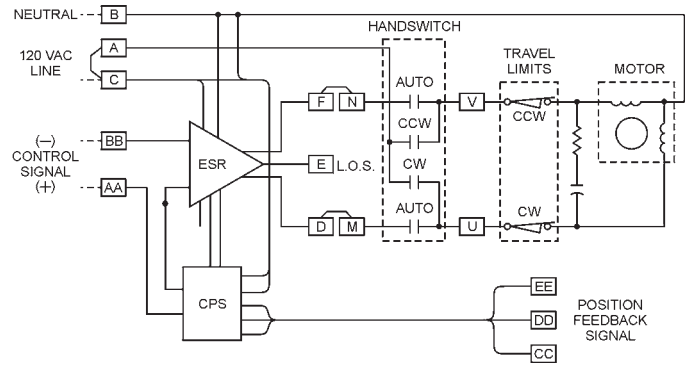
A drive can be ordered with up to four optional auxiliary switches. Wiring connections for these are described on page 23.

To disable the Handswitch, remove the jumper between terminals A and C, and add jumpers between terminals N and V, M and U.



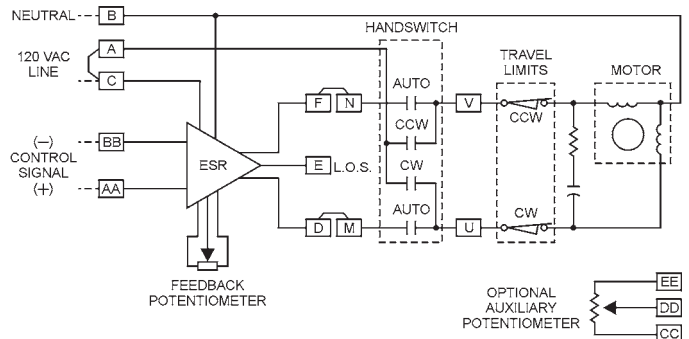
Option 8, Modulating Analog Position Control with Contactless Position Sensing

Customer must supply two wires to power the drive: One 120 V ac line (terminal C), and one neutral (terminal B). Customer must supply two wires for the modulating analog control signal: Connect to terminal AA (+) and to terminal BB (-). Customer may supply two additional wires to monitor the analog position feedback signal (see pages 14 and 15 for connections). The drive's feedback circuit power supply is derived from the 120 V ac line, therefore the feedback signal must be wired to a "4-wire" type non-powered analog input.



Option 7, Modulating Analog Position Control with Potentiometer Position Sensing

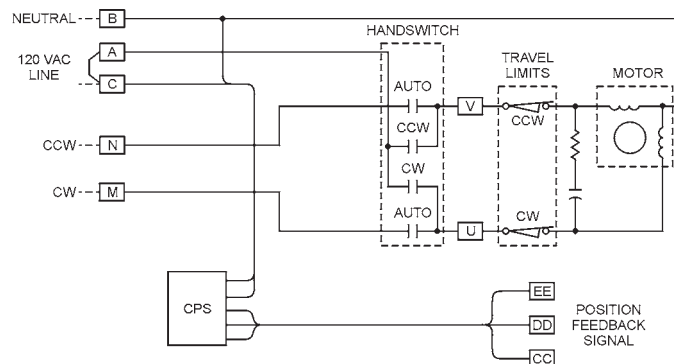
Customer must supply two wires to power the drive: One 120 V ac line (terminal C), and one neutral (terminal B). Customer must supply two wires for the modulating analog control signal: Connect to terminal AA (+) and to terminal BB (-). If position feedback monitoring is required, an optional auxiliary potentiometer can be ordered. The optional auxiliary potentiometer connects to terminals CC (reverse), DD (wiper), and EE (forward) and is compatible with standard "slidewire" style inputs.



Option 6, Modulating

Direct AC Control with Contactless Position Sensing

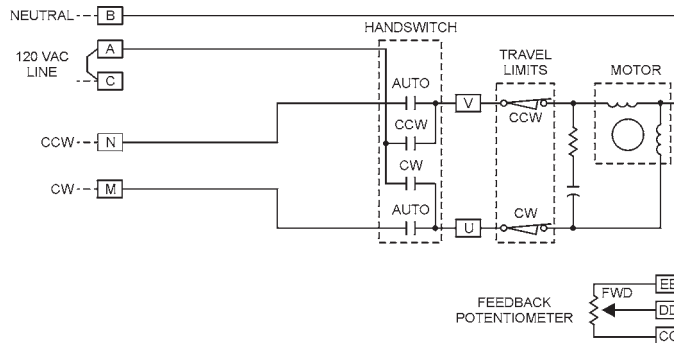
Customer must supply three wires to directly control the drive motor direction: One 120 V ac line to run CW (terminal M), one 120 V ac line to run CCW (terminal N), and one neutral (terminal B). Customer may supply two additional wires to monitor the analog position feedback signal (see pages 14 and 15 for connections). If position feedback monitoring is desired, a 120 V ac line must be connected to terminal C. The drive's feedback circuit power supply is derived from this 120 V ac line, therefore the feedback signal must be wired to a "4-wire" type, non-powered analog input.



Option 5, Modulating

Direct AC Control with Potentiometer Position Sensing

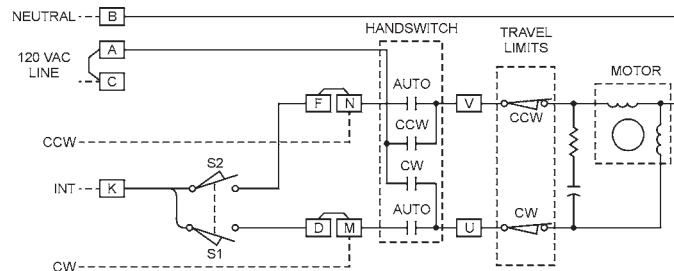
Customer must supply three wires to directly control the drive motor direction: One 120 V ac line to run CW (terminal M), one 120 V ac line to run CCW (terminal N), and one neutral (terminal B). The position feedback potentiometer connections are available at terminals CC (reverse), DD (wiper), and EE (forward).



Option 4, Multi-Position

Direct AC Control with Cam-Operated Switches to Stop Drive Travel

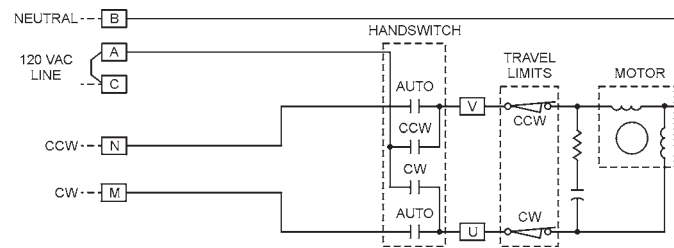
Customer must supply three wires to directly control the drive motor direction: One 120 V ac line to run CW (terminal M), one 120 V ac line to run CCW (terminal N), and one neutral (terminal B). Up to six intermediate stop positions may be specified, each requiring an additional 120 V ac line.



Option 3, Open / Close

Direct AC Control

Customer must supply three wires to directly control the drive motor direction: One 120 V ac line to run CW (terminal M), one 120 V ac line to run CCW (terminal N), and one neutral (terminal B).



240 V ac Operation

All of the options described above are available for 240 V ac operation instead of 120 V ac operation. In all cases, the power neutral is re-

placed with Line 2 of the 240 V ac, and the 120 V ac line is replaced with Line 1 of the 240 V ac.

INSTALLATION *FEEDBACK SIGNAL WIRING*

CPS-2 SIGNAL CONNECTIONS

Beck drives equipped with the Contactless Position Sensor (CPS-2) are shipped ready for installation to match the proper mA or V dc feedback range in your system.

Customer connections for feedback signal wiring on each CPS-2 model are described in the following diagrams and paragraphs. Refer to Table 13, page 50, for information on output signal ranges, output terminals, range-changing resistance values, and terminals to which the ranging resistor or jumper is connected.

NOTE: For output shaft rotation of less than 80°, refer to Calibration Procedure, page 27.

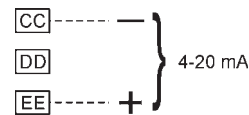
To verify that the feedback signal range is correct for your drive, see the instructions on page 28.

NOTE: Ranging resistors must be connected to the control drive output terminals. If ranging resistor change is required, use a resistor with ±1% tolerance. Resistors can be ordered from Beck.

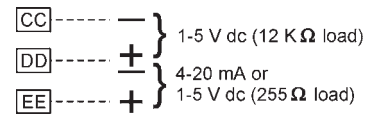
CPS-2 Model 20-3400-02, -12 Terminal Connections

1. A single 4–20 mA current output is available between terminals EE (+) and CC (-) when driving into an external load between 250 and 800 ohms. No ranging resistor is required.
2. For 4–20 mA and / or 1–5 V dc output, 4–20 mA is available across EE (+) and DD (-); 500 ohms is the maximum external load (for larger loads see Item 1 above). A 1–5 V dc signal is available across DD (+) and CC (-) into a 12 K ohm resistive load when the circuit between EE and DD is completed.

4-20 mA Signal Output



Dual Signal Output



CPS-2 Model 20-3400-03, -13 Current Feedback Terminal Connections

The universal model has current sensing terminals, which allow for various current signal ranges. Current output is available between terminals DD (+) and CC (-) with the proper ranging resistor connected across terminals DD and EE.

Units are factory-calibrated for specified signal ranges and are provided with proper resistors installed.

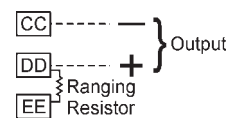
The ranging resistor value is given in Table 13, page 50, or can be calculated using the following equation:

$$R = \frac{4}{(I - .004)} \Omega$$

Where R = Resistor (Ohms) Connected from DD to EE
I = Output Current Span (Amp)

If converting to a zero-based range (a range that includes zero as an end point), refer to “Adjusting the zero potentiometer”, page 30.

Current Output



CPS-2 Model 20-3400-03, -13

Voltage Feedback

Terminal Connections

The universal model has a voltage divider network which allows for various voltage signal ranges. Voltage output ranges are available across terminals EE (+) and CC (-) with the proper ranging resistor connected across terminals CC and DD.

Units are factory-calibrated for specified signal ranges and are provided with proper ranging resistors installed. Other voltage ranges are attainable by adding a ranging resistor across terminals CC and DD.

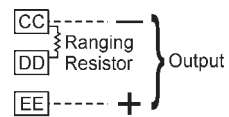
The ranging resistor value is given in Table 13, page 50, or can be calculated using the equation:

$$R = \left(\frac{V}{4} - 1 \right) K \Omega$$

Where R = Resistor Connected from CC to DD
 V = Output Voltage Span

If converting to a zero-based range (a range that includes zero as an end point), refer to “Adjusting the zero potentiometer”, page 30.

Voltage Output

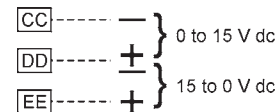


CPS-2 Model 20-3400-04, -14

Terminal Connections

The three-terminal output from these models is provided for replacing potentiometers in three-terminal potentiometer feedback applications used in many controllers. It is suitable for 0–15 V dc applications of either positive or negative polarity. CC must be connected to the negative lead from the controller, and EE to the positive lead from the controller, with DD connected to the controller lead accepting the feedback from the potentiometer wiper. These models can “source” 10 mA to the controller, or they can “sink” 2.5 mA from the controller.

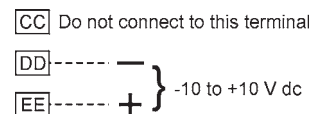
Potentiometer Equivalent



CPS-2 Model 20-3400-05, -15

Terminal Connections

Voltage signal -10 to +10 V dc is available across terminals EE (+) and DD (-). The maximum load is 5 mA.



INSTALLATION *WIRING OPTIONS*

INPUT SIGNAL OPTIONS

Beck drives configured for milliamp or DC analog modulating applications include an Electronic Signal Receiver (ESR-4). Several control options are available with the ESR-4, such as operating more than one drive with a single signal source.

The instructions below apply to applications which require a signal change or to situations calling for operation of multiple drives from a common input signal.

Input Range Change to ESR-4

If it is necessary to change the range of an ESR-4 board to receive a different input signal current, the "R-in" resistor must be changed. See Table 2, below, for the proper value, and Figure 5 on page 32 for its location on the board. It is mounted on turrets to facilitate the change. After soldering the new resistor in place, recalibrate in accordance with instructions on page 31. If a proper resistor with ±1% tolerance cannot be obtained locally, it can be ordered from Beck.

NOTE: If changing from or to an input signal range of -10 to 10 V dc, resistors R4, R34 and Jumper J1 must be changed in addition to R-in. Consult the factory for details.

Series Operation

Beck drives can be connected in series from the same signal for concurrent operation. Care must be taken to keep the polarity correct in each

drive's input terminals. Two or three drives may usually be connected in series. The number of drives that may be connected in series is limited only by the controller's (signal source) capability to feed current into the total resistance of the circuit involved. Consult the controller manufacturer's recommendations.

No change is required to the drive's calibration for series operation. An interruption in the circuit will actuate loss of input signal (L.O.S.) on the drives in the circuit.

Parallel Operation

Beck drives can be connected in parallel to the same signal for concurrent operation. Up to four drives may be connected in parallel.

For parallel operation, use ESR-4 board no. 13-2245-05 in each drive, and add a ranging resistor across input terminals AA and BB on one of the Beck drives. The value of the ranging resistor is:

$$\frac{\text{Input Resistance} \times 10 \text{ K}\Omega}{10 \text{ K}\Omega - (N) \times \text{Input Resistance}}$$

where N = the number of drives. Refer to Table 2, below, for the input resistance. For example, a 278 ohm ranging resistor should be used for four drives in parallel with a 4–20 mA input signal. If the calculated resistance is not a standard value then select the closest standard value.

A minor span adjustment is required for each drive in a parallel circuit. An interruption in the circuit to one drive will not prevent the other drives from functioning but there will be a slight calibration shift.

**TABLE 2:
ESR-4 BOARD MODELS**

INPUT SIGNAL	ESR-4 BOARD PART NO.	R-in (TOLERANCE 1%)	INPUT RESISTANCE
0-5* or 1-5 mA dc	13-2245-02	13-2511-01 1.05K ohms	1K ohms
4-20 mA dc**	13-2245-03	13-2511-03 255 ohms	250 ohms
10-50 mA dc	13-2245-04	13-2511-02 100 ohms	100 ohms
1-5 V dc**	13-2245-05	13-2512-05 20K ohms	10K ohms
-10 to 10 V dc	13-2245-08	13-2512-05 20K ohms	50K ohms

*Span and zero adjustment required.

**Standard ISA range (S 50.1/1975).

Split Range Operation

Two or three Beck drives may be operated over their full range by a portion of the controller's output signal range. The most common arrangement involves two drives operating on equal halves of the input signal range. For example, if a 4–20 mA control signal is used, the first drive would move 100% of its stroke on a signal range of 4–12 mA, while the second operates on the 12–20 mA portion of the signal. In this case, the ESR-4 boards are the same as would be used for parallel operation (13-2245-05), but calibrated to the range required for each drive. A ranging resistor must be added across input terminals AA and BB on one of the Beck drives to produce a span between 2 and 6 volts across each board for its active portion of the range. For a 4–20 mA range 3-way split, the ranging resistor range would be 425 to 1650 ohms.

Follow the steps for calibrating the input signal, page 31, for each drive unit, using half span values for the input signal. Use the proper starting point for each half-range when setting the zero; 4 mA and 12 mA. Before setting the zero on the second drive (12 mA), cut one lead of resistor R35 on the ESR-4 board. See Figure 5, page 32, to locate R35.

In a split range configuration, connect terminals E and F (L.O.S. wire) to prevent undesired “stay-in-place” operation of the second or third drive due to fast downward signal changes.

When three drives are to be operated on equal portions of the input signal, the 4–20 mA range would split into 4–9.33 mA, 9.33–14.67 mA, and 14.67–20 mA signals. A 487 ohm ranging resistor (Beck P/N 13-2510-03) is adequate. Proceed as in the case of the 2-way split, first setting the span, then the zero. When setting the ESR-4 board in the first drive, set the zero at 4 mA. Then, on the second drive, cut the R35 resistor on the board and set its zero at 9.33 mA. Before setting zero in the board of the third drive, short out the R34 resistor by adding a jumper, adjust its zero at 14.67 mA, cut resistors R35 and R36 from the board, then remove the jumper from R34. Check operation of all drives by running the input signal through its complete range. If it is necessary to recalibrate the same board later, you may jumper resistors R35 and R36 by connecting the R35 turrets together.

INSTALLATION *START-UP*

INSTALLATION—MECHANICAL

CAUTION

Whenever a control drive is being mounted on a valve, it is good practice to remove the valve from service. Observe the following precautions:

- Know what fluid is in the line.
- Wear the proper protective equipment.
- Disconnect electrical power.
- Depressurize the pipeline.
- Refer to the valve maintenance manual for specific instructions.

Installing the Drive on a Valve / Removing the Drive from a Valve

Consult the *Beck Valve Mounting Specification sheet* that was shipped with the drive for detailed instructions.

Installing the Valve / Drive Assembly

The Beck control drive can be mounted in any convenient orientation. There is no preferred operating position.

Inspect the valve and pipe flanges to be sure they are clean. Be certain that other pipelines in the area are free from pipe scale or welding slag that could damage the gasket surfaces.

Carefully lift the assembly and position the valve in pipeline. Install and tighten flange bolts according to the valve and / or gasket manufacturer's instructions.

NOTE: The valve may have undergone temperature variations in shipment. This could result in seepage past the stem seals. Refer to the valve manufacturer's maintenance instructions for packing adjustments.

START-UP INSTRUCTIONS

After the drive is mounted and its wiring connections are made, it is ready to be tested for proper operation.

NOTE: All Beck drives are shipped from the factory ready for installation; no electrical adjustments are required before placing them in operation. Each drive is set up and calibrated to the customer's specifications that were written into the equipment order.

Turn on the power supply. Operate the drive with the Handswitch and run it through its full stroke, both directions. Observe that the driven device travels through its desired stroke. If satisfactory, set Handswitch to the "AUTO" position.

If the drive is to be operated with automatic control, turn on the controller and operate the drive by varying the control signal. Check that the valve strokes in the proper direction for a change in control signal. If it does not, first check for proper wiring connections and verify control signal at the drive. If the wiring is correct, then change the direction of output shaft rotation (see page 25).

If the drive is to be push-button actuated, (options 3, 4, 5, or 6) operate the drive using the Handswitch and observe that direction of travel is correct. When travel of the driven device is satisfactory with reference to the control signal or the push-buttons, the unit is ready for operation.

OPERATION

HOUSING

Beck electronic control drives have individual cast aluminum compartments for each of the five main components: The control motor, wiring terminal block, drive train, electronic signal receiver, and control end. Gasketed covers and sealed shafts make the drives ideally suited to outdoor and high humidity environments.

Heavy cast mechanical stops built into the housing are designed to prevent accidental over-travel damage during manual cycling, and ensure that proper orientation is maintained between the output shaft and the feedback system.

CONTROL MOTOR

The Beck control motor is a synchronous inductor motor which operates at a constant speed of 72 RPM or 120 RPM in synchronism with the line frequency.

Motors are able to reach full speed within 25 milliseconds and stop within 20 milliseconds; actual starting and stopping times will vary with load.

Beck motors have double grease-sealed bearings and require no maintenance for the life of the motor.

GEAR TRAIN

The gear train is a four-stage reduction, spur gear drive constructed with only heat-treated alloy steel and ductile iron gears for durability and long life.

The drive train consists of the control motor and Handwheel, reduction gears, main gears, and output shaft. The main gear / output shaft and third stage gears are common to all units of a particular drive model. The second and first stage gears are part of the field-interchangeable gear module. Different combinations of gear modules and drive motors determine the drive's output torque and timing. See page 48 for details.

Mechanical stops are incorporated into the drive body to limit output shaft rotation to 98° on the 11-160 and about 108° on the 11-260 / 360 / 460. Mechanical transmission of output shaft position to the control end is provided by a right angle gear set driven directly by the output shaft.

SELF-LOCKING MECHANISM (SLM)

An integral part of every control motor is the self-locking mechanism. This mechanical device couples the motor to the gear train and transmits full motor torque when rotated in either direction. When the motor is de-energized, the SLM instantaneously locks and holds the output shaft in position—up to two times the rated torque of the drive.

HANDWHEEL

Every Beck control drive is furnished with a Handwheel to permit manual operation of the valve or damper without electrical power. Its solid construction design includes no spokes or projections, and turns at a safe, slow speed. The Handwheel is located at the rear of the control motor housing. The Handwheel is coupled directly to the motor shaft and rotates when the motor runs. Manual operation of the Handwheel (with electric Handswitch in "STOP" position) turns the motor and the rest of the drive train without incorporating a clutch.

HANDSWITCH

A local electric Handswitch is provided on Beck drives to permit operation at the valve, independent of the controller. As a safety feature, the Handswitch is designed so that the controller can operate the drive only when it is in the "AUTO" position. The sequence of the Handswitch is: "AUTO", "STOP", "CW", "STOP", "CCW".

In the "AUTO" position, two contacts are closed and the ESR-4 or external controller contact completes the control circuit.

In the "CW" or "CCW" positions, contacts are closed to operate the drive independently of the controller.

In the "STOP" position, all contacts remain open.

SWITCHES

Two end-of-travel switches and up to four optional auxiliary switches are provided on Beck drives. Switch cams are clamped onto the control shaft which rotates in relation to the output shaft. Cam position is field-adjustable. Switches are rated 6 A, 120 V ac. All auxiliary switch connections are made on the terminal block.

CONTROL OPTIONS

Two basic types of control are available: 120 V ac contact closure (options 3, 4, 5, and 6) and milliamp or DC analog modulating (options 7 and 8). Each option is described below.

Open / close option 3: For simple 2-position control using manual push-buttons or an automatic controller. Preset travel limit switches provide open / close operation upon closure of an automatic controller or manually operated switch. Travel limits are adjustable over the full range of travel and provide precise positioning repeatability.

Multi-position option 4: Adjustable cam operated switches provide up to six discrete stop positions upon closure of an automatic controller or manually operated switch. Three, four, five, and six predetermined position settings are possible, with precise positioning repeatability.

Direct AC control option 5: Provides continuous positioning capability over the full range of drive travel by direct AC control from either an automatic controller or manually operated switches. Includes a 1000 ohm film potentiometer for remote feedback.

Direct AC control option 6: Provides continuous positioning capability over the full range of drive travel by direct AC control from either an automatic controller or manually operated switches. Includes a Contactless Position Sensor (CPS-2) for feedback and position indication.

Modulating option 7: For automatic operation in response to milliamp or dc analog control; includes a film potentiometer for position sensing and feedback to the Electronic Signal Receiver (ESR-4).

Modulating option 8: For automatic operation, as in option 7 above; includes Contactless Position Sensor (CPS-2) for position sensing and feedback to the ESR-4.

INPUT: ELECTRONIC SIGNAL RECEIVER (ESR-4)

Beck modulating drives are equipped with precision electronic control modules (ESR-4) to receive conventional 4–20 mA or 1–5 V dc control signals directly, eliminating the need for contact protection devices, relays, switches, and reversing starters.

The ESR-4 provides for drive control with either analog or microprocessor control systems, and is designed to operate continuously in temperatures up to 185°F (85°C).

The ESR-4 requires a position feedback signal from either the CPS-2 monitor / isolator board or a film potentiometer. This feedback signal is compared to the input signal. A difference in these signals, the error, is amplified and used to actuate either of two electronic motor power switches. These switches drive the motor in the proper direction to force the error to zero. The input signal is adjustable from 50% to 400% of the 4-volt span, with the zero adjustable from -100% to +275% of span.

The ESR-4 permits two or more Beck drives to be operated by a single signal source, for series, parallel, or split range operation. See page 16 for details on these control options.

If the input signal to the Beck drive is changed, the ESR-4 allows for easy modification to accept a different signal current. An optional “Relay board” version of the ESR-4 permits operation on low voltage DC input signals (5 to 24 V dc) or, with an external diode / resistor module, on low current 120 V ac. This topic is covered on page 33.

POSITION FEEDBACK: CONTACTLESS POSITION SENSOR (CPS-2)

The CPS-2 provides a continuous feedback signal proportional to the position of the drive's output shaft. It is used for remote position indication as well as for automatic control loop feedback to the Electronic Signal Receiver (ESR-4). When used with the ESR-4, the CPS-2 includes a monitor / isolator board that delivers an isolated position feedback signal to the Electronic Signal Receiver (ESR-4). The Monitor function monitors the CPS-2 position signal and compares it to established limits. If the output exceeds normal signal conditions, the monitor relay contact opens. This relay may be used for either a remote signal indication or activation of Loss-of-Signal operation of the drive.

The position sensing function of the CPS-2 is provided by a ferrite magnetic sensing element consisting of two parts: A ferrite stator mounted on the CPS-2 circuit board and a ferrite rotor mounted on the control shaft, driven by the Beck drive's output shaft through the crown gear assembly. The electronic circuit translates the signal from the ferrite magnetic sensor into an analog position feedback signal designed to interface with electronic control systems and indicating instruments.

OPERATION

POSITION FEEDBACK: FILM POTENTIOMETER

The film potentiometer produces a voltage that is a fraction of the voltage applied across its resistive element. That voltage fraction is determined by the position of the wiper on the resistive element. The potentiometer assembly also includes two fixed resistors, one on each end of the resistive element. These resistors permit suppressed ranges as well as zero-based position feedback voltages. If position feedback is desired on drives equipped with an ESR-4 board, two film potentiometers are required: One for position feedback and the second to supply a feedback signal to the ESR-4.

STALL PROTECTION AND ANNUNCIATION

The Beck Stall Protection Module (SPM) is an optional feature for the Group 11 drives. The SPM monitors the motor current at terminals N and M. The SPM will be activated when the drive cannot reach a desired position within approximately 300 seconds.

When a stall is sensed, the SPM shuts off power to the motor and a solid state relay in the SPM changes state. The relay is rated for 120 V ac or dc, 10 VA. Two terminals connected to the solid state relay are located on the SPM. Use of the relay for annunciation of a stall is optional and will not affect the other functions of the SPM. A sensed stall condition is cleared by either reversing the motor direction command in the controller or by turning the drive power off and on. An LED is included on the SPM to show the operating status of the module.

LOSS OF SIGNAL (L.O.S.)

Beck drives equipped with the ESR-4 have the ability to move to a predetermined position upon loss of input control signal. When the input signal drops to 13% of span below the zero setting, the ESR-4 provides an annunciating signal with one of the following options:

1. STALOS = Stay in place, lock in last position. (Triac output available at terminal E for remote alarm, 0.12 to 5 A, 120 V, 50 or 60 hz)
2. REVLOS = To the 0% end-of-travel limit switch position. Connect terminal E to F.
3. FWDLOS = To the 100% end-of-travel limit switch position. Connect terminal E to D.
4. INTLOS = Move to predetermined intermediate auxiliary switch position. Consult factory.

When the input signal is lost but the power remains on, the L.O.S. switch on the ESR-4 board is energized, a red LED on the board lights and the directional switches are turned off. The output of the L.O.S. switch is connected to terminal E which is wired for one of the predetermined operating modes listed above.

When REVLOS, FWDLOS, or INTLOS is selected, an additional relay is required in order to provide the annunciating signal. This should be specified on ordering.

CALIBRATION SWITCHES

NOTE: Your Beck drive was shipped from the factory ready for installation; no electrical adjustments are required before placing it in operation. Each drive is set up and calibrated to the customer's specifications that were written into the equipment order.

Under normal operating conditions there is no need to recalibrate the control drive. However, if the application requirements change or are different than specified on the equipment order, the drive should be recalibrated according to the following procedures.

SWITCH ADJUSTMENTS

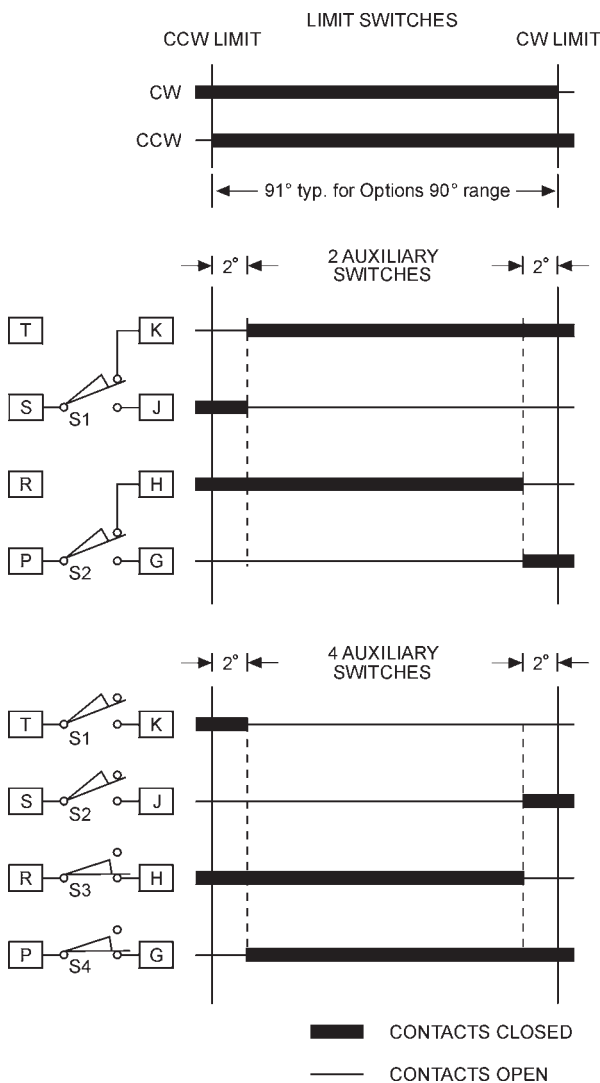
Over-travel limit switches (options 5 thru 8) are factory set $1/2^\circ$ outside each end of travel unless otherwise specified at time of order. End-of-travel limit switches (options 3 & 4) are factory set at each end of travel unless otherwise specified at time of order. Limit switches must be set inside the range of the built-in mechanical stops to prevent stalling of the motor. Limit switches can be reset to limit travel of the output shaft to any angle down to a minimum of approximately 60° . Auxiliary switches are set as shown in the illustration at left unless otherwise specified at time of order.

NOTE: The limit switches are located next to the drive body. To adjust these switches, it is necessary to remove the control end cover.

Switches are operated by cams which are clamped onto the control shaft. Setting a switch involves loosening the cam, moving the output shaft to the desired position, and positioning the cam so that it just operates the switch at that point. In the following procedure, the use of a continuity meter is recommended to determine when the switch opens or closes. If such a meter is not available, it is possible to hear the switch click as the contacts open and close.

CAUTION

Do not attach the meter or attempt to move the switch cams until the drive is disconnected from the line voltage and auxiliary switches are disconnected from external power sources.



Standard Limit and Auxiliary Switch Settings

Setting Limit Switches CW and CCW

This procedure should be used if the factory limit switch settings must be changed in the field. It is advisable to operate the drive fully in each direction, using the electric Handswitch to check switch settings before attempting to change them. Follow these instructions if they require adjustment:

Note that the direction of rotation of the drive's output shaft is the same as its control shaft for models 11-26_, 11-36_ and 11-46_. However, on model 11-16_ the shafts rotate in opposite directions.

CALIBRATION SWITCHES

SETTING TRAVEL LIMIT SWITCHES, CONT'D.

1. Remove the control end cover and extensions, if applicable, and terminal block cover (1/2" bolt heads).
2. Use the electric Handswitch to drive the control shaft so that the CW switch cam screw is accessible. Using a 7/64" hex wrench, loosen the screw so that the cam is just snug on the shaft. See Figure 1, below.
3. Move the output shaft clockwise to the desired maximum CW limit switch position (for options 5 thru 8, this position should be just outside the desired CW electronic travel position).
4. Turn the Handswitch to the "STOP" position.
5. **Disconnect power from the drive.**
6. Turn the Handswitch to the "AUTO" position.
7. Connect the continuity meter across terminals B and M. Rotate the cam until the meter shows no continuity (switch contacts open, switch clicks).
8. Tighten the cam locking screw to 5 lb-in (.56 N•m) torque.
9. Disconnect meter and turn the Handswitch to the "STOP" position.
10. Reconnect drive power.
11. Rotate the drive's output shaft in the CCW direction away from the CW limit switch position. Note the direction of rotation of the lobe of the cam. The correct cam lobe motion is away from the switch lever with the switch lever on the lower part of the cam. If not correct, return to step 2 and reset the cam to the proper orientation.
12. Rotate the output shaft again to the desired CW travel limit. If the desired stopping point is reached, the switch is properly set.

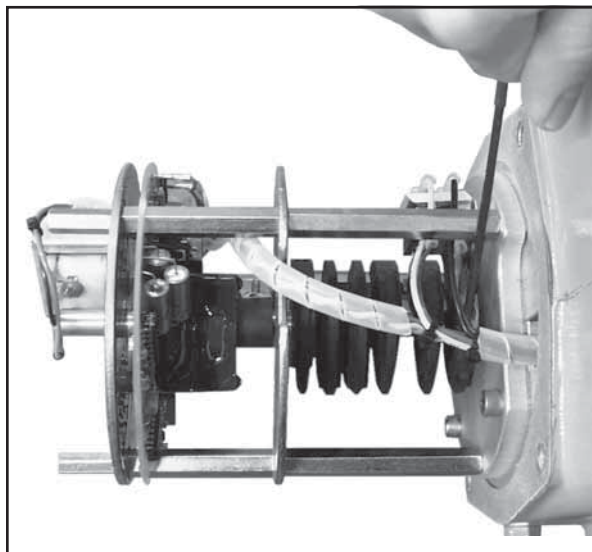


Figure 1

13. Repeat instructions for setting CCW limit switch position (noting that referenced directions of rotation should be opposite of those used for CW switch setting). Connect continuity meter across terminals B and N.
14. Replace covers and tighten cover bolts to 10 lb-ft (14 N•m) torque.
15. Rotate index (or index pointer on model 11-15_) to correspond with output shaft rotation.

Setting Auxiliary Switches

Standard switch settings for drives with 2 or 4 auxiliary switches are shown on the diagram on page 23. The heavy line indicates a closed circuit. Follow these instructions to change the operating point of auxiliary switches:

NOTE: In the following procedure, it is assumed that switch settings are to be adjusted so that contacts are open when the desired position is achieved. If they are to be adjusted to close, it may be necessary to reverse the operating mode of the switch by reversing the leads on the switch itself. Be sure to disconnect power from the switch terminals first.

1. Remove the control end cover and extensions, if applicable, and the terminal block cover (1/2" bolt heads).
2. Use the electric Handswitch to drive the shaft so that the switch cam is accessible. Using a 7/64" hex wrench, loosen the screw so that the cam is just snug on the shaft.
3. Move the output shaft to the desired position.
4. Turn the Handswitch to the "STOP" position.
5. **Disconnect power from the drive and switch terminals.**
6. Connect the continuity meter across the appropriate terminals. See the diagram on page 23 or the drive wiring diagram. Rotate the cam to operate the switch.
7. Tighten the cam locking screw to 5 lb-in (.56 N•m) torque.
8. Disconnect the meter and reconnect power.
9. Move the drive's output shaft in the desired direction so that the cam lobe moves away from the switch lever. If not correct, return to step 2 and reset the cam to the proper orientation.
10. Replace covers and tighten cover bolts to 10 lb-ft (14 N•m) torque.

CALIBRATION *DIRECTION CHANGE*

DIRECTION OF OUTPUT SHAFT ROTATION

The direction of output shaft rotation is determined by observing the end of the drive output shaft. The rotation direction desired from an increasing signal—clockwise or counterclockwise—should be specified at the time of order. If not specified, the output shaft is factory-set to rotate clockwise in response to an increasing signal.

NOTE: Changing direction of rotation does not change the setting of the auxiliary switches.

CHANGING DIRECTION OF OUTPUT SHAFT ROTATION

Procedures vary depending upon the drive model number. The number is listed on the drive nameplate. Determine the model number and refer to one of the following procedures.

CAUTION

Be sure the drive is disconnected from the line voltage and that all auxiliary switches are disconnected from the external power sources before beginning the direction change procedure.

Models 11-__3 and 11-__4

No changes are necessary for these models.

Models 11-__5 and 11-__7

NOTE: On Model 11-__7 units equipped with an auxiliary film potentiometer, the auxiliary potentiometer is mounted closest to the drive body.

1. Remove the terminal cover, control end cover and extensions, if applicable (1/2" bolt heads).
2. For model 11-__7, interchange the wire jumpers connected to terminals M and N.
3. For both models, interchange the wires connected to the ends of the potentiometer. The wire on terminal 1 or 5 should be moved to the opposite terminal. Also move the wire on terminal 2 or 4 to the opposite terminal. The wire to terminal 3 remains unchanged (i.e., if the wiring is on terminals 2 and 5, move the wire on terminal 2 to terminal 4 and move the wire from terminal 5 to terminal 1). See Table 3, page 26.

4. Reset the potentiometer wiper according to the film potentiometer calibration instructions on page 27.

Auxiliary Potentiometer Only

4. Interchange the wires connected to the ends of the potentiometer. The wire on terminal 1 or 5 should be moved to the opposite terminal. See Table 3, page 26.
5. Replace the control end cover. Torque the cover bolts to 10 lb-ft (14 N•m). Reset position indicator band.

Models 11-__6 and 11-__8

1. Remove the terminal compartment cover, control end cover and extensions, if applicable (1/2" bolt heads).
2. For model 11-__8, interchange the wire jumpers connected to terminals M and N.
3. For both models, determine the correct feedback signals from the wiring diagram supplied with your drive (CC, DD, EE).
4. FOR CURRENT FEEDBACK APPLICATIONS: Record the color and location of the feedback signal wires (for reconnection later). Remove the two feedback wires. Connect a mA meter in series with a 200 ohm load resistor.
FOR VOLTAGE FEEDBACK APPLICATIONS: Connect a voltmeter across the feedback terminals, DO NOT remove the feedback signal wires. See Table 13, page 50 for feedback terminals.
5. Reconnect drive power.
6. Drive the output shaft until the CPS-2 output is 50% of the range (e.g., for 4–20 mA signal range, set output to 12 mA).
7. Set Handswitch to "STOP" position.
8. Using a 7/64" hex wrench, loosen the CPS-2 rotor clamp.
9. Rotate the CPS-2 rotor 180° and set the output back to the mid-range (e.g., 12 mA).
10. Tighten the rotor clamp.
11. Run the drive to the 0% and 100% limits using the Handswitch. Record the CPS-2 output at these limits.
12. Subtract the outputs recorded at the two limits and compare with the desired output signal span (e.g., 16 mA for a 4–20 mA signal range). The difference between the measured span and the desired span is the span error.

Continued

CALIBRATION *DIRECTION CHANGE*

TABLE 3

STANDARD FILM POTENTIOMETER CONNECTIONS FOR ESR						
Model	Output Shaft Rotation Increasing Signal	Wire Connections To Potentiometer Terminals*				
		1	2	3	4	5
167	CW	ORG		YEL	GRN	
	CCW		GRN	YEL		ORG
267, 367, 467	CW		GRN	YEL		ORG
	CCW	ORG		YEL	GRN	

*ORG wire is ESR pin 3
YEL wire is ESR pin 4
GRN wire is ESR pin 5.

STANDARD FILM POTENTIOMETER CONNECTIONS FOR EXTERNAL FEEDBACK						
Model	Output Shaft Rotation Increasing Signal	Wire Connections To Potentiometer Terminals*				
		1	2	3	4	5
165, 167	CW	ORG		YEL		GRN
	CCW	GRN		YEL		ORG
265, 267, 365, 367, 465, 467	CW	GRN		YEL		ORG
	CCW	ORG		YEL		GRN

*ORG wire is Terminal Block location EE
YEL wire is Terminal Block location DD
GRN wire is Terminal Block location CC

CHANGING DIRECTION OF OUTPUT SHAFT ROTATION, CONT'D.

13. With the drive at the 100% limit, turn the span potentiometer to adjust the CPS-2 output signal by 1/2 of the span error calculated in step 12. Turning the span potentiometer CW increases the span equally at both ends. Turning the span potentiometer CCW decreases the span equally at both ends. See Figure 4, page 29, for the location of the span potentiometer.
14. Loosen the CPS-2 rotor clamp and rotate to achieve the desired value of maximum output signal (e.g., 20 mA for a 4–20 mA signal range). Rotation of the CPS-2 rotor moves the entire signal range up or down.
15. Tighten the CPS-2 rotor clamp to 5 lb-in torque. Maintain a 0.031" (.8 mm) clearance between the rotor clamp and stator.

16. Run the drive to the 0% and 100% limits and check the output signal for desired span. If not correct, repeat the procedure from step 2.
17. Remove the meter and resistor and reconnect the feedback wiring.
18. Replace covers and tighten cover bolts to 10 lb-ft (14 N•m) torque. Reset the position indicator band.
19. Model 11-__8: Check ESR-4 board calibration by following the "Checking Calibration Procedure" on page 31.

CALIBRATION *FEEDBACK SIGNAL*

FEEDBACK SIGNAL CALIBRATION

Feedback signal calibration is necessary to ensure that the signal correctly corresponds to the drive's output shaft position. All drives are shipped with the feedback calibrated for full 90° travel of the output shaft unless otherwise specified at the time of order. Minimum shaft travel available on Group 11 drives is 60°.

The procedure to check and set feedback calibration varies by model number. The model number is listed on the drive nameplate. Determine the model number and refer to the proper procedure below.

NOTE: The travel limit switches must be properly adjusted before the feedback signal is calibrated. The feedback signal must be calibrated before the input signal can be calibrated.

Film Potentiometer Calibration Models 11-__5 and 11-__7

NOTE: On Model 11-__7, units equipped with an auxiliary film potentiometer, the auxiliary potentiometer is mounted closest to the drive body.

When properly adjusted, the auxiliary potentiometer feedback signal should be maximum with the drive output shaft at the 100% (maximum input signal) position. At 50% of travel the signal should be mid-span. At the 0% position, the signal should be minimum.

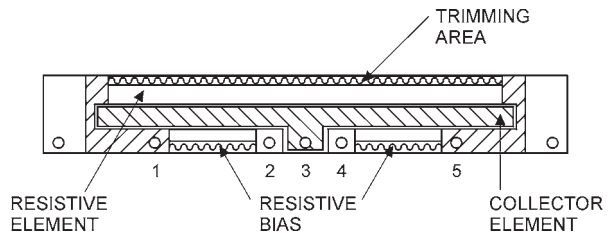
On control option 7 units, potentiometer feedback to the ESR-4 board should be 0.52 V dc at the minimum input signal position and 2.41 V dc $\pm 6\%$ at the maximum input signal position.

If either the auxiliary or main potentiometer on option 7 units is out of calibration, or if the feedback potentiometer on option 5 units is out of calibration, the procedure to recalibrate is the same.

1. Remove the ESR cover and the control end cover (1/2" bolt heads).
2. Loosen the clamping screw (use 9/64" hex wrench) on the potentiometer wiper so that it is just snug on the shaft.
3. Use the Handswitch to run the drive to the 0% position.
4. On Model 11-__7, set the wiper on the potentiometer for 0.52 volt feedback to the ESR. The feedback can be read on the ESR board at TP3 and TP2. See Figure 5 on page 32. The feedback can also be read at the yellow

and green leads at the film potentiometer. On models 11-__5, set the wiper about 5 degrees above the position where the minimum output is reached, or as required by the control system.

NOTE: Be sure that the wiper spans the resistor and collector elements equally, and does not touch the areas of low resistance at either end of the film element.



5. Tighten the clamping screw to 5 lb-in (.56 N•m) torque.
6. Operate the drive between the electrical limits. Verify that the feedback signal is properly adjusted.
7. Use the manual Handwheel to run the drive to the mechanical limit; do not over-torque, as damage may result.
8. Check that the wiper does not come off the resistive element. This may be verified by monitoring the output voltage and ensuring it does not fall from maximum value. If not correct, return to step 2.
9. Replace the control end cover and the ESR cover. Torque the cover bolts to 10 lb-ft (14 N•m).

CPS-2 Calibration

Model 11-__6 and 11-__8

These models are equipped with a Contactless Position Sensor (CPS-2) for position sensing and feedback. On model 11-__8, the CPS-2 also delivers a feedback signal to the Electronic Signal Receiver (ESR-4). Adjusting the remote feedback signal will automatically adjust the signal to the ESR-4 on these models.

CPS-2 units are designed to provide position feedback without contacting or wiping surfaces. On option 8 units, the CPS-2 includes a Monitor / Isolator board which detects high and low out-of-limit conditions. The Monitor function monitors the CPS-2 position signal and compares it to established limits. If the output exceeds normal signal conditions, the monitor relay contact opens. This relay may be used for either a remote signal indication or activation of Loss-of-Signal operation of the drive.

Continued

CALIBRATION *FEEDBACK SIGNAL*

CPS-2 CALIBRATION, CONT'D.

The CPS-2 provides infinite resolution by incorporating a ferrite rotor on the control shaft and a ferrite stator mounted on the position sensing circuit board. To make feedback signal adjustments, adjust the span, then change the position of the rotor on the control shaft to adjust the zero.

Checking Feedback Signal Calibration

The following procedure should be followed to check CPS-2 calibration:

Tools required:

- mA / V dc Multimeter
- 1/2" Combination Wrench
- 200 ohm Resistor

1. Put electric Handswitch in "STOP" position.
2. Remove the terminal block cover and the control end cover (1/2" bolt heads).
3. Determine the correct feedback terminals from the wiring diagram supplied with your drive (CC, DD, EE).
4. FOR CURRENT FEEDBACK APPLICATIONS: Record the color and location of the feedback signal wires (for reconnection later). Remove the two feedback wires. Connect a mA meter in series with a 200 ohm load resistor.
FOR VOLTAGE FEEDBACK APPLICATIONS: Connect a voltmeter across the feedback terminals. DO NOT remove the feedback signal wires. See Table 13, page 50, for feedback terminals.
5. Drive the output shaft through its full range and check the feedback signal. When properly adjusted, the feedback signal should be maximum with the drive's output shaft at the 100% (maximum input signal) position. At 50% travel the signal should be mid-span. At 0%, the signal should be minimum. If not correct, proceed with the calibration procedure.

Note: Tolerance on factory calibration is $\pm 0.5\%$ of span.

Calibration Procedure

Adjustment of the CPS-2 is necessary if the signal range requires an increase or decrease in value relative to the drive's output shaft rotation. Calibrate by turning the span potentiometer CW to increase the gain of the CPS-2. This has the effect of increasing the output at the high end and lowering the output at the low end equally.

Signal span is determined by the CPS-2 model and ranging resistor selected.

CAUTION

Do not adjust the zero potentiometer to shift the span.

To adjust the span, turn the span potentiometer on the CPS-2 circuit board. The span potentiometer adjusts the CPS-2 so that a drive output shaft rotation from 80° to 90° produces the specified output signal range.

For output shaft rotation of between 60° and 79°, it may be necessary to remove resistor R8 (100 K ohm) to change the range of the span adjustment. An R8 value of 100 K ohms produces shaft output range of 80° to 100°; R8 = 249 K ohms produces shaft output range of 70° to 79°; and removing R8 produces shaft output range of 60° to 69°. See Figure 4, page 29, for location of R8 (positioned on raised turrets).

Tools required for calibration:

- mA / V dc Multimeter
- 3/32" Screwdriver
- 7/64" Hex Wrench
- 1/4" Screwdriver
- 1/2" Combination Wrench
- 1/32" (.8 mm) Thickness Feeler Gauge
- 200 ohm Resistor

1. Put electric Handswitch in "STOP" position.
2. Remove the terminal block cover and the control end cover (1/2" bolt heads).
3. Determine the correct feedback terminals from the wiring diagram supplied with your drive (CC, DD, EE).
4. FOR CURRENT FEEDBACK APPLICATIONS: Record the color and location of the feedback signal wires (for reconnection later). Remove the two feedback wires. Connect a mA meter in series with a 200 ohm load resistor.
FOR VOLTAGE FEEDBACK APPLICATIONS: Connect a voltmeter across the feedback terminals. DO NOT remove the feedback signal wires. See Table 13, page 50, for feedback terminals.
5. Run the drive to the 0% and 100% limits using the Handswitch. Record the CPS-2 output at these limits.
6. Subtract the outputs recorded at the two limits and compare with the desired output signal span (e.g., 16 mA for a 4–20 mA signal range). The difference between the measured span and the desired span is the span error.

Continued

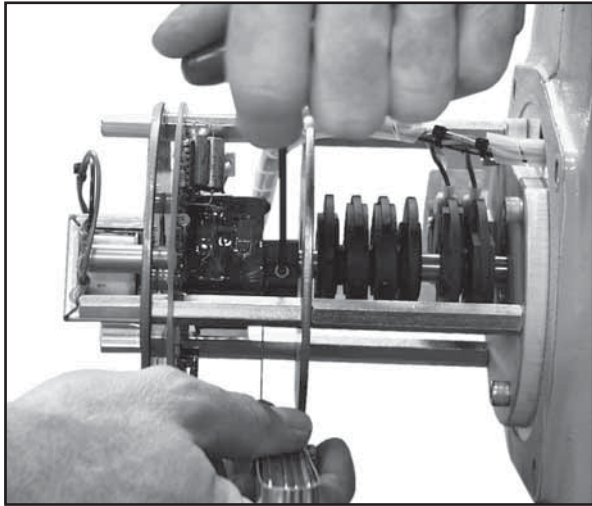
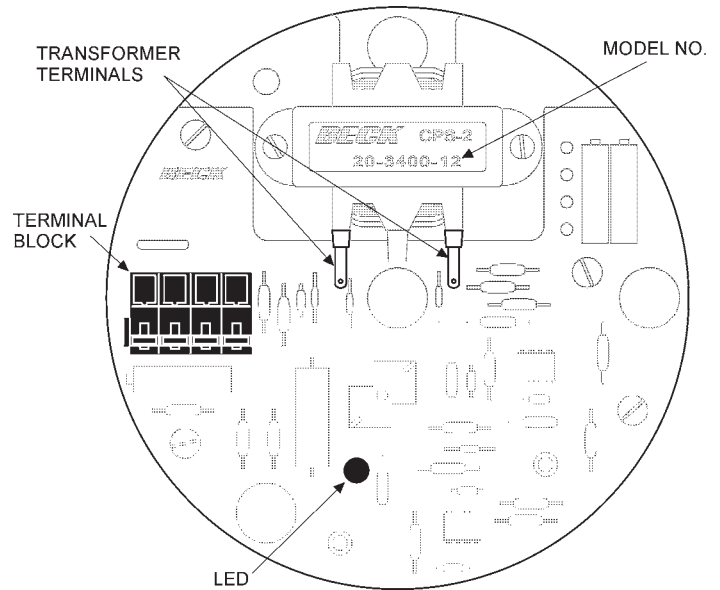
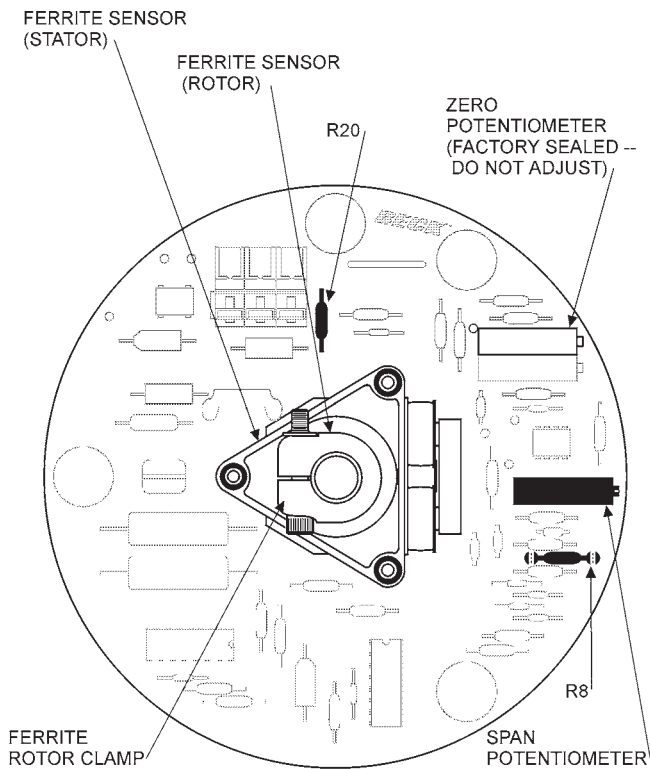


Figure 2

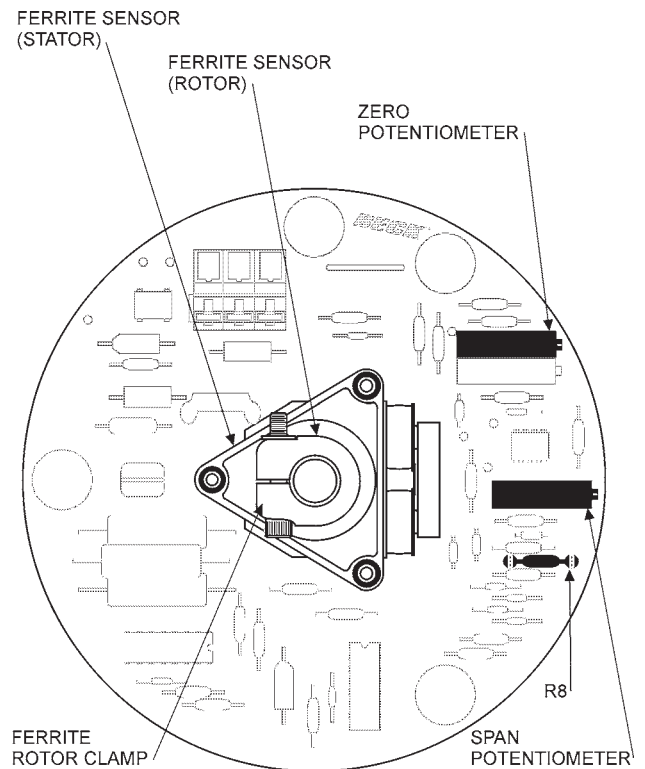


CPS-2 MONITOR / ISOLATOR ASSEMBLY

Figure 3



CPS-2 POSITION SENSOR
MODELS 20-3400-02, -04, -05, -12, -14, -15



CPS-2 POSITION SENSOR
MODELS 20-3400-03, -13

Figure 4

CALIBRATION *FEEDBACK SIGNAL*

CALIBRATION PROCEDURE, CONT'D.

7. With the drive at the 100% limit, turn the span potentiometer to adjust the CPS-2 output signal by 1/2 of the span error calculated in step 6. Turning the span potentiometer CW increases the span equally at both ends. Turning the span potentiometer CCW decreases the span equally at both ends. See Figure 4, page 29, for the location of the span potentiometer.
8. Loosen the CPS-2 rotor clamp and rotate to achieve the desired value of maximum output signal (e.g., 20 mA for a 4–20 mA signal range). Rotation of the CPS-2 rotor moves the entire signal range up or down.
9. Tighten the CPS-2 rotor clamp to 5 lb-in torque. Maintain a 0.031" (.8 mm) clearance between the rotor clamp and stator.
10. Run the drive to the 0% and 100% limits and check the output signal for desired span. If not correct, repeat the procedure from step 5.
11. Remove the meter and resistor and reconnect the feedback wiring.
12. Replace covers and tighten the cover bolts to 10 lb-ft torque.
13. Model 11-__8: Check ESR-4 board calibration by following the "Checking Calibration Procedure" on page 31.

Adjusting the Zero Potentiometer

The zero potentiometer is provided on CPS-2 models 20-3400-03 and -13 to change from a suppressed zero to a zero-based range (e.g., from 1–5 V dc to 0–16 V dc). The zero is adjustable from -5% to +30% of span.

CAUTION

The zero is factory sealed on all CPS-2 units except 20-3400-03 and -13. Do not attempt to adjust the zero on other models as misadjustment of feedback signal and monitor / isolator functions of the ESR-4 will result.

NOTE: Do not adjust the zero potentiometer to shift calibration. Adjust the rotor position only to shift calibration.

The following example is given to illustrate how the zero is adjusted to effect a range change from 1–5 V dc to 0–16 V dc.

1. Install the 1–5 V dc unit as a 1–5 V dc range. Do not make any adjustments other than setting the rotor position.
2. Remove jumper from terminals CC to DD and replace with a 3.01 K ohm resistor (see Table 13 on page 50). This shifts the range to 4–20 V dc.
3. Using a voltmeter at the appropriate output terminals, adjust the zero potentiometer with the drive at minimum input signal position so that output reads 0 V dc. This changes the range to 0–16 V dc.

FEEDBACK SIGNAL MONITOR / ISOLATOR

CPS-2 models 20-3400-12, -13, -14, and -15 are provided with a Monitor / Isolator board that delivers an isolated position feedback signal to the Electronic Signal Receiver (ESR-4). The Monitor function monitors the CPS-2 position signal and compares it to established limits. If the output exceeds normal signal conditions, the monitor relay contact opens. This relay may be used for either a remote signal indication or activation of Loss-of-Signal operation of the drive.

No adjustments should be made on the Monitor / Isolator board.

Signal Monitor Sensing Operation

A red LED indicator and an SPST relay are mounted on the Monitor / Isolator board to indicate that power is on and that the CPS-2 output signal is within normal range. The contacts open at -4% and +104%, and close at -1% and +101%.

The SPST relay is rated for 0.1 A resistive at 100 V dc.

Loss of Signal Operation

Drives equipped with Electronic Signal Receivers (ESR-4) are configured so that the input control signal is connected through the feedback signal monitoring relay on the monitor board of the CPS-2. The Loss-of-Signal (L.O.S.) function of the ESR-4 may therefore be activated when the CPS-2 signals are outside the normal range (see above). It is possible to have an out-of-range CPS-2 signal trigger the L.O.S. mode—contact the factory for details and instructions. For more information on the L.O.S. function, review the following section on Input Signal Calibration.

CALIBRATION *INPUT SIGNAL*

INPUT SIGNAL CALIBRATION

All drives equipped for milliamp or DC analog modulating applications include an Electronic Signal Receiver (ESR-4). The ESR-4 board consists of a voltage regulator, a signal amplifier, an error amplifier, and three solid-state output switches.

The ESR-4 board controls the position of the Beck drive according to the input signal it receives. A feedback signal is delivered to the board from either a potentiometer or the CPS-2, which is compared with the input signal. The error signal is then amplified and used to actuate either of two switches to drive the output shaft clockwise or counterclockwise until the signals balance and the error is zero.

The third output switch is energized when the signal falls below a given setting. The L.O.S. output can be used to drive the output shaft to a predetermined position. See section on L.O.S., page 33, for further details.

NOTE: The input signal is calibrated relative to the output (feedback) signal. Therefore, the shaft travel limit switches must be properly adjusted and the feedback signal calibrated before the input signal can be calibrated.

Checking Calibration

Using the input control signal, drive the output shaft through its complete range. Check the position feedback signal to confirm that a 10% input signal delivers a 10% position, a 50% signal delivers a 50% position, and a 90% signal delivers a 90% position. If the feedback signals do not correspond to the appropriate input signals, then the ESR-4 must be calibrated. The tolerance on factory calibration is $\pm 0.5\%$ of span.

CAUTION

The signal circuit on ESR-4 units is not grounded. If grounding is required, connect terminal BB in the terminal compartment to ground, either on the drive body or externally.

Calibration Tips

The input signal can be varied by the automatic controller, but if that is impractical, a test box may be used. Connect the test box to positive terminal AA and negative terminal BB of the terminal block in place of the controller input.

Span and zero adjustments are located near the edge of the ESR-4 board (see Figure 5, page 32). Monitor the "FWD" and "REV" lamps to make adjustments. When the drive is balanced (with Handswitch in "AUTO" and not at an end-of-travel limit) or in L.O.S. mode, both lamps are on. When the output shaft is moving, the lamp designating its direction of travel goes out. When the drive reaches its end of travel before balance is achieved, the lamp will stay out. Trim the adjustment so that the drive just reaches the limit switch and the motor does not run. Clockwise rotation of either span or zero adjustment causes the output shaft to drive toward the zero (minimum input signal) position.

Calibration Procedures

NOTE: Two calibration procedures are described below. The first procedure is to be followed if the span is in error by less than 15%. If the span is in error by more than 15% follow the second procedure.

Tools required:

- 3/32" Screwdriver
- 1/2" Combination Wrench
- 1/4" Screwdriver

If the span is in error by less than 15%:

1. Remove the ESR cover and the terminal compartment cover (1/2" bolt heads).
2. Turn the Handswitch to the "AUTO" position.
3. Remove the controller output signal wires from terminals AA and BB. Record the wire color location for reconnection at a later time.
4. Connect a portable signal source, positive to terminal AA and negative to terminal BB.
5. Adjust the signal source to minimum signal (e.g., 4 mA for 4–20 mA input). The drive runs to the 0% position and stops.
6. Adjust the zero potentiometer CCW until the drive motor runs. Both the "FWD" and "REV" lamps will light and remain lit.
7. Adjust the zero potentiometer CW in small increments until the "REV" lamp goes out and the motor does not run.
8. Adjust the portable signal source output to maximum signal (20 mA). The drive runs to the 100% position and stops.
9. Adjust the span potentiometer CW until the drive motor runs and both the "FWD" and "REV" lamps light and remain lit.
10. Adjust the span potentiometer CCW in small increments until the "FWD" lamp goes out and the motor does not run.

Continued

CALIBRATION *INPUT SIGNAL*

CALIBRATION PROCEDURES, CONT'D.

11. Adjust the signal source to minimum signal (4 mA) and recheck the zero potentiometer adjustment.
12. Reinstall the input signal wires, remove the test box (if used), replace the compartment covers and tighten the cover bolts to 10 lb-ft (14 N•m) torque.

For a span error greater than 15%:

1. Remove the ESR cover and the terminal compartment cover (1/2" bolt heads).
2. Turn the Handswitch to the "AUTO" position.
3. Short input terminals AA and BB.
4. Short out resistor R35 temporarily with a clip lead (see Figure 5, this page, for location). Board has conformal coating. Take extra care to ensure proper connection. NOTE: Drive will run in CW direction.
5. Using a 3/32" screwdriver, turn the zero potentiometer CW in small steps until the REV lamp goes out and the motor does not run.
6. Remove the short on input terminals and, using the system controller or a portable signal source, apply an input signal equal to the span (e.g., 16 mA for 4–20 mA span). NOTE: The drive may run.
7. Using a 3/32" screwdriver, turn the span adjustment potentiometer CW until the drive runs, then CCW until the drive just reaches the 100% position ("FWD" lamp out, motor off).
8. Remove the clip lead on resistor R35 so that it is not shorted. Apply 100% (full range) position signal (e.g., 20 mA).
9. Turn the zero potentiometer CCW (may require 10–15 turns) to position the drive at the 100% position ("FWD" lamp out, motor off).
10. Adjust the signal source output to the minimum signal (e.g., 4 mA). The drive will run to 0%, then the motor will stop.
11. Adjust the zero potentiometer CCW until both lights remain on.
12. Adjust the zero potentiometer CW in small increments until the "REV" lamp goes out and the motor does not run.
13. Adjust the signal source output to maximum signal (20 mA). The drive runs to 100%.
14. Adjust the span potentiometer CW until the drive motor runs and both the "FWD" and "REV" lamps remain on.
15. Adjust the span potentiometer CCW in small increments until the "FWD" lamp goes out and the motor does not run.

16. Adjust the portable signal source for minimum signal (4 mA). The drive will run to 0%. Recheck the zero potentiometer adjustment.
17. Reinstall the input signal wires, remove the test box (if used), replace the compartment covers and tighten the cover bolts to 10 lb-ft (14 N•m) torque.

Span

The basic span adjustment of the ESR-4 is 2–6 volts dc. This is adjustable with the 20-turn span potentiometer. To make the span adjustable from 2–9 volts dc, remove resistor R4. To make the span adjustable from 9–12 volts dc, remove jumper wire J1. To make the span adjustable from 12–16 V dc remove R4 and J1. See Figure 5, below, for location of R4 and J1.

Zero (Supp.)

The basic zero adjustment is -20% to 100% of span. This is adjustable with the zero potentiometer. For 2-way split range applications, remove resistor R35 to shift the zero adjustment to 20% to 150% of span. For 3-way split range operation, remove resistors R35 and R36 to shift the zero adjustment to 150% to 275%. For other split range applications, consult factory for adjustment. See Figure 5, below, for location of R35 and R36.

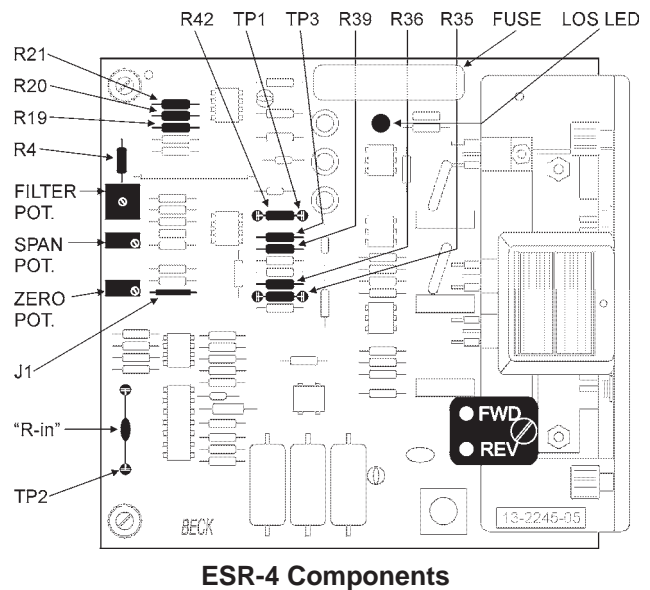


Figure 5

Filter Adjustment

The input filter is adjusted at the factory for maximum attenuation of disturbances on the input signal (fully CW). This introduces a 1% drift (with 60 second timing) in response to a loss of input signal when “stay-in-place” is selected. If this is objectionable or if livelier response is desired, the filter action can be reduced by turning the filter adjustment potentiometer CCW a sufficient amount. Fully CCW takes the filtering out completely but in some cases may lead to undesirable cycling. If this happens, turn the adjustment CW until the cycling is damped out. See Figure 5, page 32 for location.

Deadband Adjustment

The deadband values of 0.6% for CPS-2 or film potentiometer operation are chosen to satisfy the requirements of most control systems. If excessive process and / or signal noise is present, the drive may be subject to unnecessary cycling. It is recommended that excessive noise be reduced at the source in order to prevent unnecessary cycling. This will improve process control and prolong component life.

If it is not possible to eliminate the excessive noise, the drive’s deadband can be widened; however, this will reduce the resolution of the drive. Widening the deadband to 1% can be accomplished by removing resistor R39. Further change of the deadband is possible by changing the value of R42 (only after R39 is removed). Various values and corresponding deadbands are listed below. See Figure 5, page 32, for the location of R39 and R42.

R39	R42	Deadband
Remove	4.99 M ohms	1.0%
Remove	3.30 M ohms	1.6%
Remove	2.20 M ohms	2.4%

L.O.S. TRIP POINT

If the input signal drops below a predetermined value, the L.O.S. feature is activated. The standard factory setting of this feature is approximately 13% of the signal span below the minimum signal value. For example, if the input signal is 4–20 mA, 13% of that 16 mA span is 2.08 mA. Therefore, the L.O.S. trip point would be 1.92 mA (4.0 mA minus 2.08 mA). If the input signal is 1–5 V, 13% of that 4 V span is 0.52 V. Therefore, the L.O.S. trip point would be 0.48 V (1.0 V minus 0.52 V).

If it is necessary to change the L.O.S. trip point, this may be done by replacing resistors on the ESR board. Consult the factory for details.

SQUARE FUNCTION

With the optional Square Function ESR-4 board (Beck part no. 13-2245-09) the drive output shaft position changes proportionally to the square of the input signal as in Table 4.

For input signal calibration, follow the calibration procedure beginning on page 31. Component locations are the same as shown in Figure 5, page 32.

TABLE 4

Input Signal (mA)	Standard Output (% of Span)	Square Function, Actual Output Position (% of Span)
4.0	0	0
5.6	10	1
12.0	50	25
15.2	70	49
18.4	90	81
20.0	100	100

RELAY BOARD OPERATION AND CALIBRATION

The Relay board is a solid-state interface to permit switching large control motor currents with low-voltage dc or low-current ac inputs.

Relay Board Calibration

The purpose of calibrating the Relay board is to ensure that clockwise and counterclockwise input signals are balanced; for example, if a 24 V dc signal runs the drive in the clockwise direction, a –24 V dc signal should run the drive in the counterclockwise direction, and a zero signal should prevent the drive from running.

Two calibration procedures are described on the following page. The first applies to low-current 120 V ac input signals. The second applies to low-voltage 24 V dc pulsed input signals.

CALIBRATION *INPUT SIGNAL*

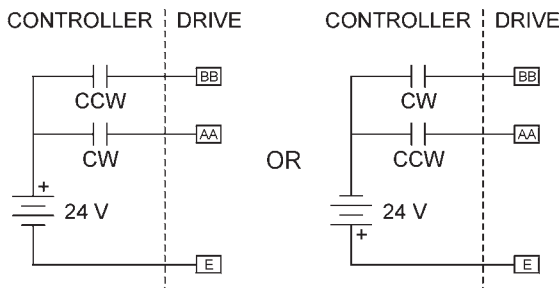
RELAY BOARD CALIBRATION, CONT'D.

Low-current 120 V ac Relay Board Calibration Procedure (Relay Board 13-2245-50):

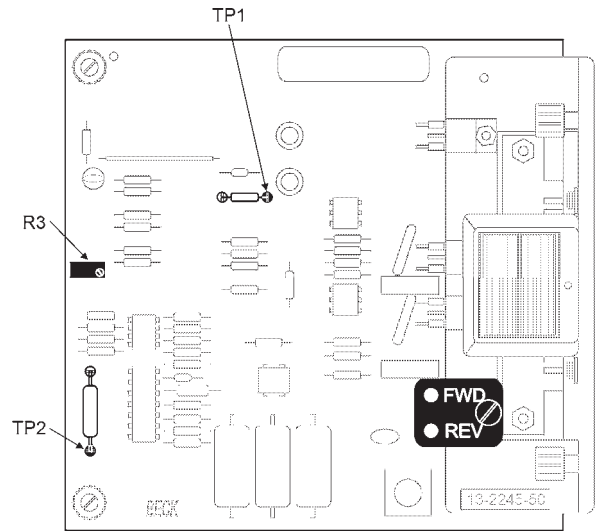
1. Disconnect drive from line voltage and remove terminal cover and ESR cover (1/2" bolt heads).
2. Remove input signal wires from terminals AA and BB.
3. Attach voltmeter to test points TP1 (+) and TP2 (-). See Figure 6, this page, for location of test points on the Relay board.
4. Turn on line voltage.
5. Adjust potentiometer R3 to bring meter reading to +0.17 volts ± 0.01 V dc. See Figure 6 for location of potentiometer R3.
6. Disconnect drive from line voltage and reconnect input signal wires to terminals AA and BB.
7. Check operation of drive with system signals.
8. Replace covers and tighten cover bolts to 10 lb-ft (14 N·m) torque.

Low-voltage 24 V dc Relay Board Calibration Procedure (Relay Board 13-2245-51):

1. Disconnect drive from line voltage and remove terminal cover and ESR cover (1/2" bolt heads).
2. Remove input signal wires from terminals AA and BB.
3. Attach voltmeter to test points TP1 (+) and TP2 (-). See Figure 7, this page, for location of test points on the Relay board.
4. Turn on line voltage.
5. Adjust zero potentiometer R3 for -0.2 V at TP1 with neither input signal applied. See Figure 7 for location of zero potentiometer R3.
6. Adjust span potentiometer R2 for -0.2 V at TP1 with both input signals applied simultaneously. See Figure 7 for location of span potentiometer R2.
7. Disconnect drive from line voltage and reconnect input signal wires to terminals AA and BB.
8. Check operation of drive with system signals.
9. Replace covers and tighten cover bolts to 10 lb-ft (14 N·m) torque.

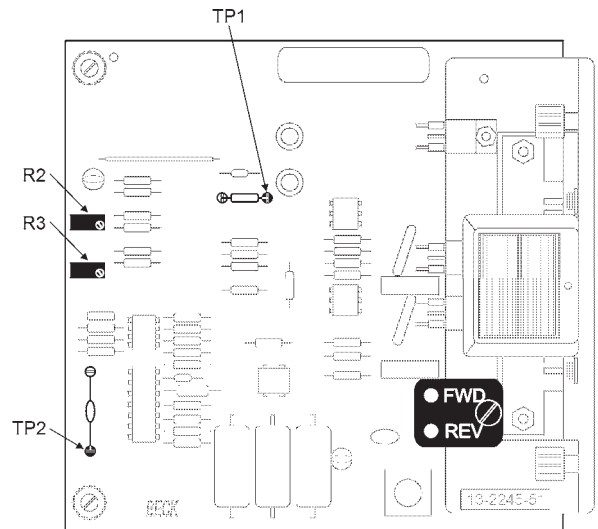


NOTE: When used in low-current AC applications, the Relay board provides a load of 10 mA to the controller. If the controller requires a larger minimum load, the user must provide additional load external to the control drive using resistors from each input to neutral. Since these resistors generate heat, sufficient means for cooling must be provided.



Low Current 120 V ac
Relay Board Components

Figure 6



Low Voltage 24 V dc
Relay Board Components

Figure 7

MAINTENANCE *ROUTINE*

Beck drives require only a minimum of routine maintenance. A visual inspection is in order to verify that the connection to the final control element is intact and operating normally. If vibration is present, check the electrical terminal connections and other hardware for tightness.

LUBRICATION

Periodic lubrication is not required on Beck control drives. However, it is recommended that during major shutdowns or outages, the drives in the most severe applications be inspected to determine the need to relubricate the drive gear train.

To inspect the gears, remove the gear module assembly on the 11-260, -360 and -460. On Model 11-160, the gears are attached to the motor, which can be removed for inspection. Clean the gears thoroughly, removing all old lubrication.

Examine the gear teeth, shaft bore, and gear shafts for signs of excessive wear, scoring, or other damage. If evidence of this damage is present, the drive should be returned to the factory for a detailed examination of the main gear, which requires complete disassembly of the drive. See "HOW TO OBTAIN SERVICE" on page 55.

If there is no evidence of damage to the gearing, recoat the teeth and shaft bores of all gears with a heavy layer of Fiske Lubriplate GR-132 or equivalent (GR-132 is an E.P. grease with polymer additives). The ball bearing on the output shaft and crown gear shaft have double grease seals and require no maintenance for the life of the bearings. Inspect all grease seals and replace any that show wear. Reassemble the drive.

MAINTENANCE *COMPONENT REPLACEMENT*

This section covers replacement of many components of the drive. Note that some components are not field-repairable. Refer to the drive outline dimension drawings on pages 6–9 and to the cutaway drawings on pages 45–47 for location of components on the drive.

If it should ever be necessary to replace the output gear, shaft, or output shaft bearings, a major overhaul is required and the drive should be returned to the factory. During a major overhaul, the factory repair department will update the drive to include all possible engineering improvements.

Gaskets

During routine service, inspect the cover, motor, and change gear plate gaskets for wear or damage. In order to protect internal components, worn or damaged gaskets and O-rings should be replaced.

To remove, scrape all of the old adhesive and gasket material from the body housing and cover. Cement the new gasket to the drive body using a gasket cement such as 3M #847 Rubber and Gasket Adhesive, or equivalent.

The gasket between the body halves should be replaced if the body halves are taken apart. No cement is used on this gasket. Trim the outside edges of the gasket after assembly as required.

Seals

Worn or damaged output shaft, control end shaft, and motor shaft seals should be replaced to prevent damage to internal bearings and drive train parts.

To remove the shaft seal, push the blade of a small screwdriver along the shaft and under the seal lip. CAUTION: The seal is approximately 1/4" (6.35 mm) wide. Do not force the screwdriver blade beyond the width of the seal; damage to the shaft bearing could result. Pry up on the seal and force it out of the housing. Clean the shaft and housing then press in the replacement seal with the closed side facing outward.

Bearings

The Beck control drive contains ball bearings on the output shaft, control end shaft, and motor shaft. Bushings and thrust washers are used on combination gears. Field replacement of these components is not recommended.

Motor shaft bushings in the body of the 11 -160 and 11-460 can be replaced. TIP: To remove, fill the bushing with a heavy grease.

Select a drive pin that slip fits into the bushing. Insert the pin into the bushing and tap with a mallet. This will force the bushing out of the body casting.

Motor

The control motor is not field-repairable. Disassembly of the motor will result in a loss of torque that can only be restored by returning the motor to the factory for re-magnetizing.

To remove the motor, first disconnect the motor wires in the terminal compartment of the control drive. In the 11-260, -360, and -460 drives, remove the terminal block and plate as an assembly. Remove the black wire from the terminal post, cut the red motor wire near the red-yellow-red butt joint and disconnect the green wire from the motor capacitor. Remove the mounting bolts and motor. Carefully slide the motor out of the drive body.

To install the motor, insert the three-wire sleeve through the wire hole in the motor mount and into the terminal compartment. Carefully slide the motor into the drive body. Rotate the motor shaft if necessary to engage the pinion with the first combination gear. Install motor mounting bolts and torque to recommended values. See pages 6–9 for torque values. Reconnect the motor wires. See the following section for reinstalling the terminal plate.

Motor Resistor and Capacitor

The motor resistor and capacitor are located under the terminals in the terminal compartment. To replace a resistor or capacitor, remove the terminal cover. In the 11-260, -360, and -460, remove the terminal plate. Remove the existing part and transfer the wires one at a time to the replacement part. Inspect the terminal plate gasket and replace if necessary. To ensure a watertight seal between the plate and gasket, coat the gasket with a thin film of grease before replacing the terminal plate. Torque the screws to 3 lb-ft (4 N•m).

Limit and Auxiliary Switches

Complete switch assemblies may be replaced. It is not possible to replace individual switches. To replace switch assemblies, remove the control end cover (1/2" bolt heads) and extensions, if applicable. Remove the screws holding the switch assembly to the plate and slide it out to the side.

Transfer the wires one at a time to the replacement assembly using the push-on lugs provided. Install the replacement assembly and note that it rotates around one screw to permit an adjustment of the cam-to-switch lever spacing and switch operating point. To properly set the switch, use a .030" (.75 mm) shim between the cam and switch lever and loosely position the switch assembly so that the switch is just actuated. The switch lever should be on the low or minimum radius portion of the cam when setting the switches. DO NOT overstress the switch lever. Tighten both screws to 10 lb-in (14 N•m) torque and remove the shim. When properly adjusted the switch lever should remain in contact with the cam throughout the control drive travel.

Adding Switches

It is usually possible to add switches to a control drive in the field. Remove the control end cover (1/2" bolt heads) and extensions, if applicable. If the drive has no auxiliary switches, it is possible to add up to four switches.

If the control shaft does not have unused switch cams, extra switches may be added, but additional parts will be required. Consult the factory, giving the control drive model and serial number so that a correct list of parts required may be supplied to you.

Install wiring onto the switch push-on lugs and route the wires into the control drive terminal area. Remove the terminal cover and solder wires to the underside of the terminal assembly according to the wiring diagram included with the

new switch assembly. Install the new switch assembly and adjust according to the instructions above. See Table 6, page 44, for switch part numbers.

SLM Friction Surface

In normal service, the SLM friction surface will last for five to ten years. Faster rates of wear can occur in any drive operating near its rated torque and with a high frequency or continuous rate of modulation. The following procedure can be used to determine the amount of wear life remaining on the friction surface: Turn the Handswitch to STOP. Carefully turn the Handwheel back and forth. There should be free play before the motor pinion turns. If there is free play in the Handwheel (up to one tenth of a full Handwheel rotation), the SLM has sufficient wear life. If there is no free play in the Handwheel, the drive may not hold position and the friction surface should be replaced.

If the friction surface needs to be replaced, order the appropriate SLM kit as shown in Table 5, below. Two kits are available: SLM Friction Kit and SLM Rebuild Kit.

The SLM Friction Kit typically consists of friction material, spring pin, steel shims, control motor gasket, thrust washer, terminal joints, slip-on terminal and instruction sheet.

The SLM Rebuild Kit typically consists of friction material, spring, spring pin, thrust washer, pinion, steel balls, locking disc, steel shims, control motor gasket, terminal joints, slip-on terminal and instruction sheet.

Continued

**TABLE 5:
SLM PART NUMBERS**

Motor Part Number	SLM Friction Kit	SLM Rebuild Kit	Instruction Sheet Only
11-160 20-2700-20 20-2701-20	12-8060-05 12-8060-05	12-8060-15 12-8060-16	80-0016-05 80-0016-05
11-260, -360 20-2704-21 20-2705-21	12-8060-07 12-8060-07	12-8060-17 12-8060-18	80-0016-07 80-0016-07
11-460 20-2201-21, -22, -23 20-2201-31, -32, -33	12-8060-01 12-8060-03	12-8060-11 12-8060-13	80-0016-01 80-0016-02

MAINTENANCE COMPONENT REPLACEMENT

SLM FRICTION SURFACE, CONT'D.

See Figure 8, below, for component identification.

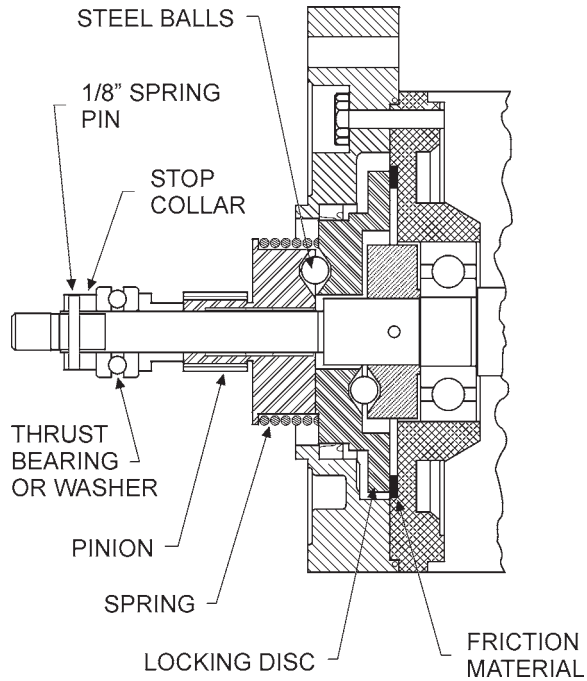


Figure 8

Handswitch

To replace the Handswitch, remove the terminal cover, and then remove the terminal plate (11-260, -360, and -460 only). Clip the five wires from the old Handswitch. Remove the knob and the nut under the knob to remove the switch. Install the new Handswitch as shown in Figure 9, below. Splice the wires color for color. Inspect the terminal plate gasket and replace if necessary. To ensure a watertight seal between the plate and the gasket, coat the gasket with a thin film of grease before replacing the terminal plate.

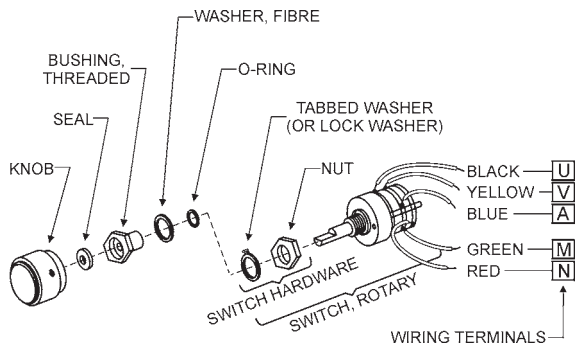


Figure 9

Torque the screws to 3 lb-ft (4 N•m). Do not over-torque. Replace the terminal cover. Torque bolts to 10 lb-ft (14 N•m).

NOTE: When the Handswitch is turned fully clockwise, "AUTO" should be indicated. The standard Handswitch part number is 20-3300-17.

ESR-4 Board

Field service of the ESR-4 board is not recommended. The factory maintains a stock of replacement boards for immediate shipment. To replace the ESR-4 board, remove the Electronic Signal Receiver compartment cover (1/2" bolt heads). Loosen the four captive thumb screws holding the board to its mounting pads. Note the "L" shaped mounting bracket on the end of the board. To remove the board, pull the mounting bracket away from its mating surface with a rocking motion. See Figure 10, below.

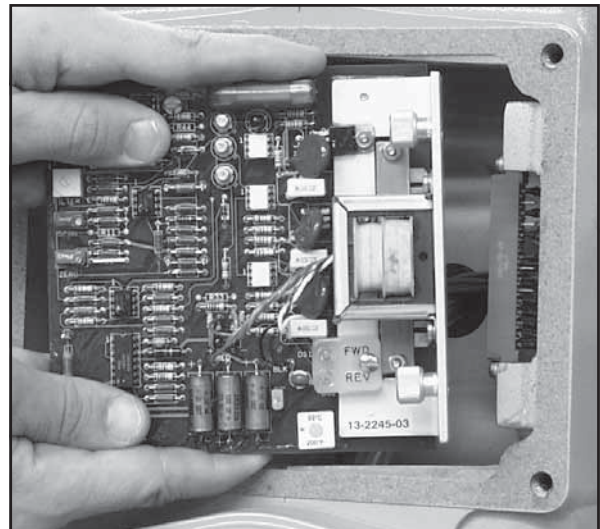


Figure 10

To install an ESR-4 board, lightly press the board connector into its receptacle until the mounting bracket is flush with its mounting surface. Tighten the four captive thumb screws and replace the compartment cover. Torque cover bolts to 10 lb-ft (14 N•m).

CPS-2

Field repair of the CPS-2 assembly is not recommended. The factory maintains a stock of replacement assemblies for immediate shipment. If it is necessary to replace the CPS-2, replace both the rotor and stator / circuit board assembly. When returning the CPS-2 to the factory for service, include the rotor and stator / circuit board assembly. Do not separate the stator or circuit boards from their mounting plates. It is recommended that the rotor be held inside the stator with rubber bands and the hex studs be re-attached to the mounting plate for protection during shipment.

To remove the CPS-2:

1. Run the control drive to its midpoint of travel with the local Handswitch. (If the standard rotation of 90° has been reduced to 80°, the midpoint of travel is 40°.)
2. Disconnect 120 V ac power to the drive. Remove the terminal compartment and control end covers (1/2" bolt heads).
3. Record the wire colors on the terminal block of the CPS-2 (see Figure 3, page 29), then disconnect the wires. The terminals are spring-loaded. To remove a wire, press the tip of a 3/32" screwdriver into the slot at the top of the small, white lever. Push down on the lever to open the spring-loaded contact and release the wire.
4. Pull the wires from the monitor board and transformer back through the wire hole in the CPS-2.
5. Loosen and remove the 3 hex studs that clamp the CPS-2 in place. Support the in-board hex stud with a wrench as the outboard stud is loosened.
6. Slide the CPS-2 stator assembly off the three mounting bolts.
7. Note the position of the rotor clamp, then loosen the rotor clamp screw and remove the rotor from the shaft.

To install the new CPS-2:

1. Remove the rotor from the replacement CPS-2 assembly. Slide the rotor, clamp end first, onto the control shaft as close to the mounting plate as possible. Leave the clamp loose. Position the clamp in the same general location as the one removed previously.
2. Slide the new CPS-2 assembly over the studs and rotor. Replace the hex nuts but do not tighten. Carefully slide the rotor back into the CPS-2 assembly. Twist the rotor while sliding

to prevent damage to the assembly. Tighten hex nuts to 5 lb-ft (7 N•m).

3. Thread the wires through the wire holes in the CPS-2 and reconnect them to the transformer and terminal block.
4. Restore 120 V ac power to the drive and connect a meter to the output.

FOR CURRENT FEEDBACK APPLICATIONS: Record the color and location of the feedback signal wires for re-connection later. Remove the two feedback wires. Connect a mA meter in series with a 200 ohm load resistor.

FOR VOLTAGE FEEDBACK APPLICATIONS: Connect a voltmeter across the feedback terminals. DO NOT remove the signal feedback wires.

5. Insert a 0.031" (.8 mm) feeler gauge between the rotor clamp and stator. Position the clamp 0.031" (.8 mm) from the stator.
6. Rotate the rotor on the control shaft until the output on the mA or voltmeter reads 50% of signal span, then tighten the clamp to 5 lb-in (7 N•m) torque.
7. Check the feedback signal calibration as described on page 28.

MAINTENANCE *TROUBLESHOOTING*

If your unit contains a Stall Protection Module (SPM), refer to publication 80-0017-03, "Troubleshooting".

CONDITIONS	POSSIBLE CAUSES	CORRECTIONS
<p>1. Control drive will not run in either direction with input signal applied to ESR-4 board. No lamps lit on ESR-4 board.</p>	<p>a. Handswitch left in wrong position. b. No 120 V ac line supply. c. Fuse F1 open. d. External auto / man switch in wrong position (Position-All). e. ESR-4 board failure. f. Jumpers between terminals F-N and D-M are not connected.</p>	<p>a. Return Handswitch to "AUTO" position. b. Check fuses and switches in power panel. c. Check for possible shorts, then replace fuse. Use only Beck part no.13-2230-03 for proper protection of triacs. d. Return switch to "AUTO" position. e. Replace ESR-4 circuit board. See page 38. f. Connect jumpers.</p>
<p>2. Control drive will not run in either direction with input signal applied to ESR-4 board. CPS-2 LED light out and jumper removed from monitor board relay.</p>	<p>a. No power. b. Control drive positioned beyond calibrated limits. c. CPS-2 rotor position not set properly. d. CPS-2 not calibrated correctly. e. CPS-2 failure.</p>	<p>a. Check power source. Check CPS-2 power supply voltage. Check CPS-2 power transformer. b. Position drive with Handwheel and check limit switch settings. c. Set CPS-2 rotor position. See page 39. d. Calibrate CPS-2. See page 27. e. Replace CPS-2. See page 39.</p>
<p>3. Control drive runs in one direction only in "AUTO" and both directions with Handswitch on "CW" and "CCW".</p>	<p>a. ESR-4 zero adjustment incorrect. b. Handswitch failure. c. Loss of input signal with "REV-LOS" or "FWDLOS" selected. d. ESR-4 circuit board failure. e. Loss of feedback signal. f. Jumper between F-N or D-M (F-M or D-N) not connected.</p>	<p>a. Readjust ESR-4 zero. See Input Signal Calibration, page 31. b. Check continuity from terminal N to V and M to U with Handswitch in "AUTO" position. See wiring diagram. c. Check input signal. d. Replace ESR-4 circuit board. See page 38. e. Check signal from CPS-2 or potentiometer at TP3 on ESR-4. f. Connect jumper.</p>
<p>4. Loss of ESR-4 signal lamp lights (red LED) with input signal applied.</p>	<p>a. ESR-4 zero adjustment incorrect. b. Input signal reversed. c. ESR-4 circuit board failure. d. Slidewire-equipped drive with ESR-4 board calibrated for CPS-2. e. Incorrect film potentiometer setting. f. Control signal wired through CPS-2 monitor relay. Monitor LED lamp is out.</p>	<p>a. Readjust ESR-4 zero. See Input Signal Calibration, page 31. b. Check polarity of input signal. Terminal AA (+), Terminal BB (-). c. Replace ESR-4 circuit board. See page 38. d. Cut R22 and R39 resistors and recalibrate ESR-4 board. See Figure 5, page 32. e. Reset film potentiometer. See page 27. f. Control drive position beyond calibrated range. Use Handswitch or Handwheel to put drive within normal operating range.</p>

CONDITIONS	POSSIBLE CAUSES	CORRECTIONS
5. Control drive runs in the wrong direction with input signal applied.	<ul style="list-style-type: none"> a. Input signal reversed. b. Drive configured for wrong direction of travel. 	<ul style="list-style-type: none"> a. Check polarity of input signal. Terminal AA (+), terminal BB (-). b. See page 25 for changing direction of shaft rotation.
6. Control drive does not follow input signal until maximum or minimum signal is reached, then drives uncontrollably to limit.	<ul style="list-style-type: none"> a. Wire jumpers on terminals M and N are reversed or potentiometer end connections are reversed. b. CPS-2 feedback out of phase with control motor. 	<ul style="list-style-type: none"> a. Change direction of shaft rotation; see page 25. Check correct film potentiometer connections. See Table 3, page 26. b. Restore proper phasing of CPS-2 feedback with control motor. See page 27.
7. Control drive motor oscillates in "AUTO" mode.	<ul style="list-style-type: none"> a. Feedback potentiometer dirty. b. Excessive noise on input signal. c. Physical obstruction (e.g., valve jammed or load greatly exceeds rating of drive). d. ESR-4 circuit board failure. e. Excessive wear in gear train or bearings. 	<ul style="list-style-type: none"> a. Clean or replace potentiometer. b. Check setting of input filter. May require increased deadband setting if oscillation remains with maximum filter setting. See page 33. c. Check operation with Hand-switch and remove obstruction if present. Handswitch bypasses ESR-4 board. d. Replace ESR-4 circuit board. See page 38. e. Replace worn drive train parts.
8. Control drive motor erratic or runs in wrong direction in automatic or manual operation.	<ul style="list-style-type: none"> a. Control motor winding open. b. Control motor capacitor shorted or open. c. Control motor resistor open. 	<ul style="list-style-type: none"> a. Replace control motor. See page 36. b. Replace capacitor. See page 36. c. Replace resistor. See page 36.
9. Control drive will not run in either direction or one direction in automatic or manual operation.	<ul style="list-style-type: none"> a. Limit switch failure. b. Handswitch failure. 	<ul style="list-style-type: none"> a. Replace limit switch. See page 36. b. Replace Handswitch. See page 38.
10. Control drive erratic while driving from 90° to 0° and runs normally from 0° to 90° in "AUTO".	<ul style="list-style-type: none"> a. Feedback potentiometer dirty. Loss of feedback voltage drives the unit toward the 100% limit. 	<ul style="list-style-type: none"> a. Clean feedback potentiometer with mild soap and water.
11. Control drive runs uncontrollably to some position, then oscillates.	<ul style="list-style-type: none"> a. Feedback potentiometer open. 	<ul style="list-style-type: none"> a. Replace feedback potentiometer.
12. Control drive does not stop at normal or desired limit of shaft travel.	<ul style="list-style-type: none"> a. ESR-4 span or zero adjusted incorrectly. b. Limit switches adjusted incorrectly. c. Loss of input signal. Check LED on ESR-4 circuit board. d. Limit switch failure. e. CPS-2 calibration incorrect. 	<ul style="list-style-type: none"> a. Recalibrate ESR-4 board. See Input Signal Calibration, page 31. b. Readjust limit switches. See page 23. c. Restore input signal to control drive. d. Replace limit switch. See page 36. e. Calibrate CPS-2. See page 27.

MAINTENANCE *TROUBLESHOOTING*

CONDITIONS	POSSIBLE CAUSES	CORRECTIONS
13. Loss of input signal feature does not function.	<ul style="list-style-type: none"> a. CPS-2 equipped control drive used with ESR-4 board calibrated for slidewire. b. Incorrectly set potentiometer. c. CPS-2 calibration incorrect. 	<ul style="list-style-type: none"> a. Reconnect R22 and R39 resistors and recalibrate. See page 31. b. Reset potentiometer. See page 27. c. Calibrate CPS-2. See page 27.
14. Control drive drives to 100% limit with small change in input signal.	<ul style="list-style-type: none"> a. Feedback potentiometer power supply shorted. b. ESR-4 circuit board failure of 2.7 V power supply (feedback potentiometer only). c. Wiper and low end of feedback potentiometer reversed. d. Open potentiometer element. e. CPS-2 feedback out of phase with control motor. 	<ul style="list-style-type: none"> a. Check potentiometer and wiring for shorts. b. Replace ESR-4 circuit board. See page 38. c. Check wiring on feedback potentiometer for proper connections. d. Replace potentiometer. e. Restore proper phasing of CPS-2 feedback with motor control. See page 27.
15. Control drive drives to 100% and stays.	<ul style="list-style-type: none"> a. Handswitch left in "CW" / "CCW" position. b. Potentiometer open or complete loss of contact with wiper. c. Loss of input signal when FWD-LOS is selected. ESR-4 LED on. d. ESR-4 zero adjustment incorrect. e. ESR-4 circuit board failure. f. CPS-2 feedback out of phase with control motor. g. Jumper between terminal F-N (F-M) not connected. h. CCW / CW limit switch failure. 	<ul style="list-style-type: none"> a. Return Handswitch to "AUTO" position. b. Check potentiometer and replace if necessary. c. Restore input signal to drive. d. Readjust ESR-4 zero. See Input Signal Calibration, page 31. e. Replace ESR-4 circuit board. See page 38. f. Restore proper phasing of CPS-2 feedback with control motor. See page 27. g. Connect jumper. h. Replace limit switch. See page 36.
16. Control drive travel very non-linear: <ul style="list-style-type: none"> a. e.g., 4–19 mA change on input causes drive to drive from 0% to 30%; 19–20 mA change drives 30% to 100%. b. Response normal from zero to mid-range; then runs to 100%. c. Output is 25% with 50% input signal, but OK at 0% and 100% inputs. 	<ul style="list-style-type: none"> a. Wiper and high end of feedback potentiometer reversed. b. CPS-2 power supply failure. c. Drive has square function ESR-4. 	<ul style="list-style-type: none"> a. Check feedback potentiometer for proper connections. b. Check CPS-2 power supply voltage. See item 21. b. on this chart.
17. L.O.S. operates at too high a signal level.	<ul style="list-style-type: none"> a. Special requirement. 	<ul style="list-style-type: none"> a. Change L.O.S. trip point. See page 33.

CONDITIONS	POSSIBLE CAUSES	CORRECTIONS
18. CPS-2 LED goes out during normal travel.	a. CPS-2 not calibrated correctly.	a. Calibrate CPS-2. See page 27.
19. Potentiometer or CPS-2 output decreases when it should increase.	a. CPS-2 rotor position not set for proper rotation. b. End connections on potentiometer reversed.	a. Reset CPS-2 rotor position. See page 39. b. See potentiometer calibration, page 27.
20. CPS-2 output non-linear.	a. CPS-2 rotor position not set properly. b. CPS-2 zero potentiometer mis-adjusted.	a. Reset CPS-2 rotor position. See page 39. b. Refer to factory.
21. CPS-2 output does not reach maximum signal, but low end calibration is correct.	a. Output is overloaded: <ul style="list-style-type: none"> • load resistance is too low for voltage range. • load resistance is too high for current range. b. Low Voltage: <ul style="list-style-type: none"> • CPS-2 power failure. c. CPS-2 rotor not set properly. d. CPS-2 zero potentiometer mis-adjusted.	a. Check load resistance against suggested feedback signal terminal hook-up. See page 50. b. Check line voltage at CPS-2 transformer terminals 1 and 3. Check CPS-2 voltage at resistor. Check CPS-2 power supply voltage across capacitors C8 (13 V, except -05.15 V), C9 (15 V), C10 and C11 (28 V). c. Reset CPS-2 rotor position. See page 39. d. Refer to factory.
22. CPS-2 out of calibration.	a. CPS-2 zero potentiometer inadvertently reset.	a. Refer to factory.
23. CPS-2 signal will not calibrate down to 4 mA.	a. Not enough load on meter circuit. b. Unit being calibrated for shorter than 80° rotation.	a. Connect 200 ohm resistor in series with meter. b. Remove R8. See calibration, page 28.
24. Control drive does not stay in place with power off.	a. SLM friction surface worn.	a. Replace SLM friction surface. See page 37.
25. Control motor runs but output shaft does not move in one or both directions.	a. SLM failure.	a. Replace control motor. See page 36.
26. Control drive equipped with Modulating option 5 or 6 and an optional Relay board does not run reliably in one or both directions in "AUTO".	a. Controller output requires a greater holding current than the Relay board load draws.	a. Check the controller output required AC holding current. If greater than 10 mA, additional load must be provided. See page 34.

APPENDIX *SPARE PARTS*

RECOMMENDED SPARE PARTS

It is recommended that certain replacement parts be stocked for quick availability in the event that service of your Beck control drive is required. The types of parts are listed in Table 6, below.

HOW TO ORDER SPARE PARTS

Select the needed parts from the spare parts list given below. Specify the drive's model / serial number (example: 11-368-031891-01-02) given on the nameplate to allow the factory to verify the part selection. Parts may be ordered by mail, telephone or fax, with the confirming order sent to the factory (see back cover).

TABLE 6: RECOMMENDED SPARE PARTS

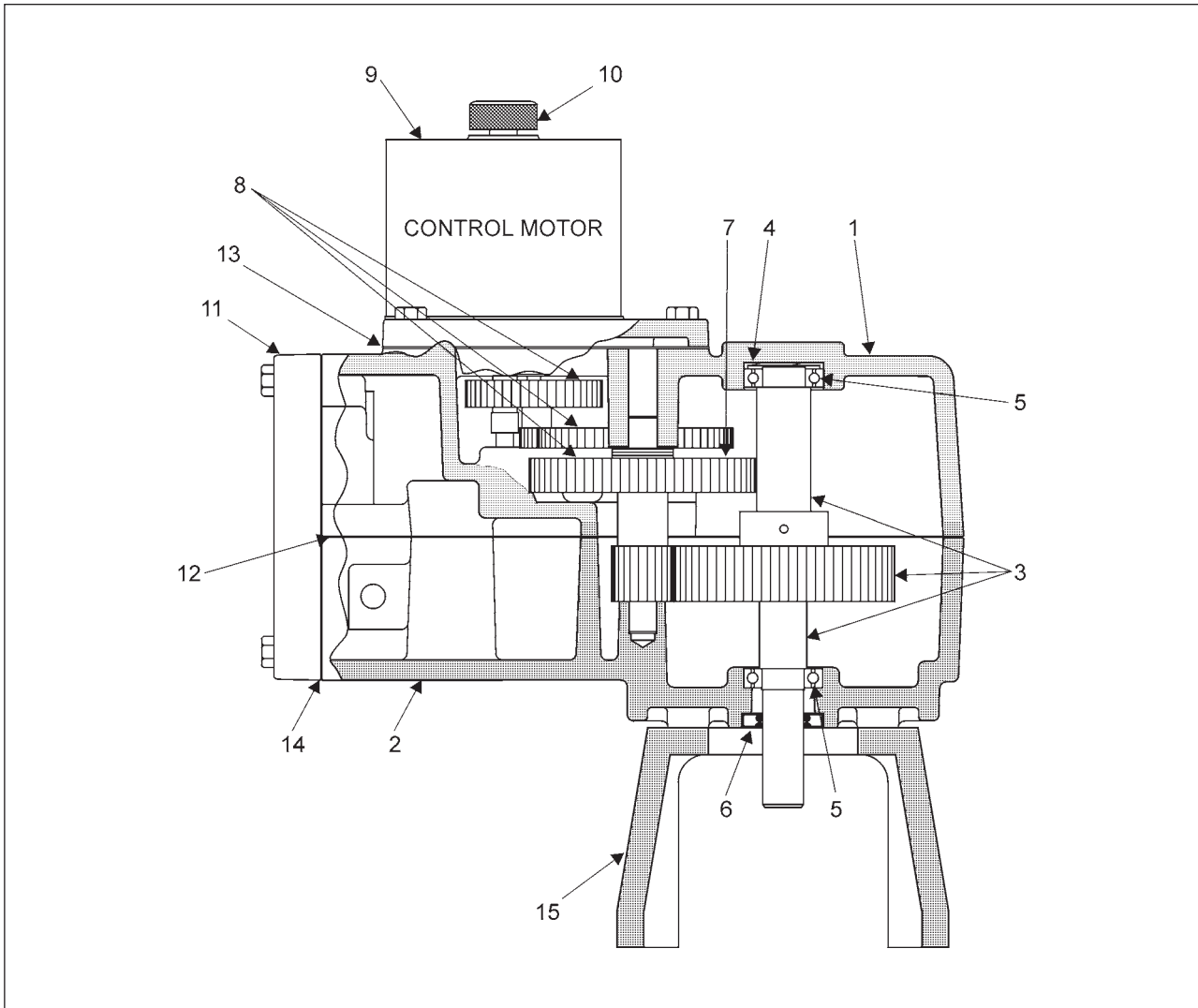
DESCRIPTION	PART NO.	DESCRIPTION	PART NO.
Limit switch assembly	20-3202-10	ESR-4 circuit board (Model 11-__7 and 11-__8 only)	13-2245-XX. See Table 1, page 10, for part number based on input signal
Auxiliary switch assembly (2 switches)	20-3202-11	Fuse, 6 A 250 V	13-2230-03
(4 switches)	20-3202-12	Relay Board (Model 11-__5 and 11-__6 only)	13-2245-XX. See Table 1, page 10, for part number based on input signal
Gasket set: Model 11-160	20-3110-01	CPS-2 (Model 11-__6 and 11-__8 only)	20-3400-XX. See Table 1, page 10, for part number based on output signal
Model 11-260	20-3110-02	SLM Friction Kit: Model 11-160	
Model 11-360	20-3110-02	Model 11-260 / -360	See Table 5, page 38
Model 11-460	20-3110-03	Model 11-460	
Control motor	See Table 7, below		
Motor resistor	See Table 7, below		
Motor capacitor	See Table 7, below		
Film Potentiometer (Model 11-__5 and 11-__7 only)	20-3060-03		

TABLE 7: MOTORS, CAPACITORS AND RESISTORS

USED ON MODEL NO.	MOTOR PART NO.	VOLTAGE	HERTZ	AMP.	CAPACITOR PART NO.	VALUE	RESISTOR PART NO.	VALUE
11-160	20-2700-20	120	60	.17	14-2840-02	2 µf	11-5802-03	500Ω
			50	.17	14-2840-13	3 µf	11-5802-03	500Ω
	20-2701-20	120	60	.32	14-2840-11	4 µf	11-5802-02	475Ω
			50	.32	14-2840-11	4 µf	11-5802-02	475Ω
11-260 and 11-360	20-2704-21	120	60	.35	14-2840-16	5 µf	20-1971-13	220Ω*
			50	.35	14-2840-19	7 µf	20-1971-13	220Ω*
	20-2705-21	120	60	.56	14-2840-05	8 µf	20-1971-12	110Ω*
			50	.56	14-2840-06	10 µf	20-1971-12	110Ω*
11-460	20-2201-21, -31	120	60	1.25	14-2840-17	15 µf	20-1971-03	75Ω*
			50	1.25	14-2840-16	5 µf	20-1971-03	75Ω*
					14-2840-17	15 µf		
	20-2201-22, -32	120	60	2.20	14-2840-15	25 µf	20-1971-04	37.5Ω*
			50	2.20	14-2840-05	8 µf	20-1971-04	37.5Ω*
					14-2840-15	25 µf		
	20-2201-23, -33	120	60	3.00	14-2840-15	25 µf	20-1971-06	18Ω*
						14-2840-09	6 µf	
			50	3.00	14-2840-15	25 µf	20-1971-10	24Ω*
						14-2840-05	8 µf	
				14-2840-09	6 µf			

*This is a resistor assembly.

APPENDIX COMPONENTS

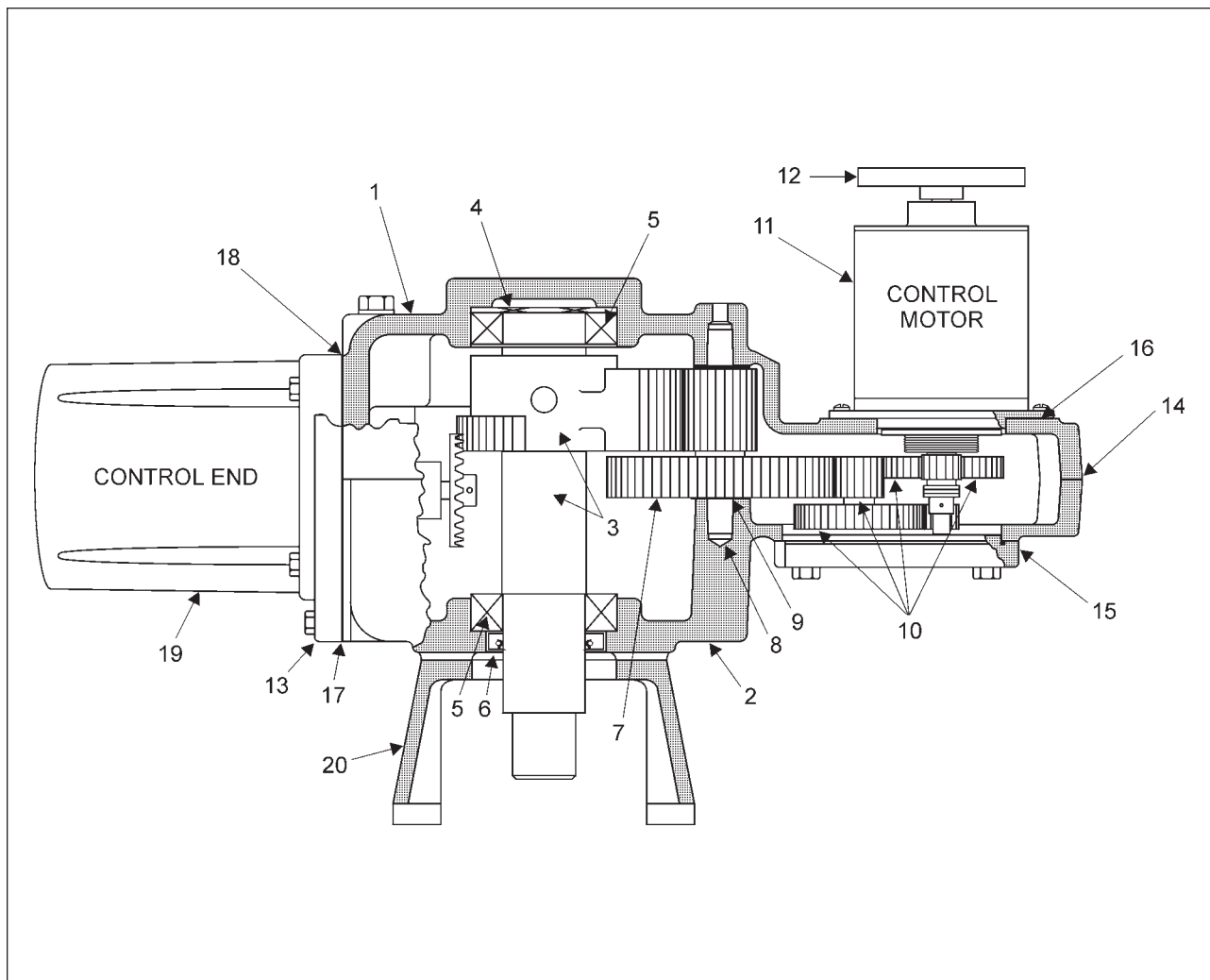


**TABLE 8:
DRIVE COMPONENTS FOR MODEL 11-160**

ITEM NO.	DESCRIPTION	ITEM NO.	DESCRIPTION
1	Body rear	11	Terminal compartment cover
2	Body front		ESR compartment cover
3	Output shaft assembly and main gear	12	Gasket, body
4	Spring washer	13	Gasket, control motor
5	Ball bearing, output shaft	14	Gasket, terminal cover
6	Seal, output shaft		Gasket, ESR cover
7	Gear, 3rd combination		Gasket, control end cover
8	Gear module assembly, see Table 11, page 49, for part number		Control end cover
9	Control motor, see Table 7, page 45, for part number		Control end cover extension
10	Handwheel		Terminal block
			Barrier, insulator, terminal compartment
		15	Bracket

Note: To ensure exact replacement parts, include all nameplate data of the Beck drive with the order.

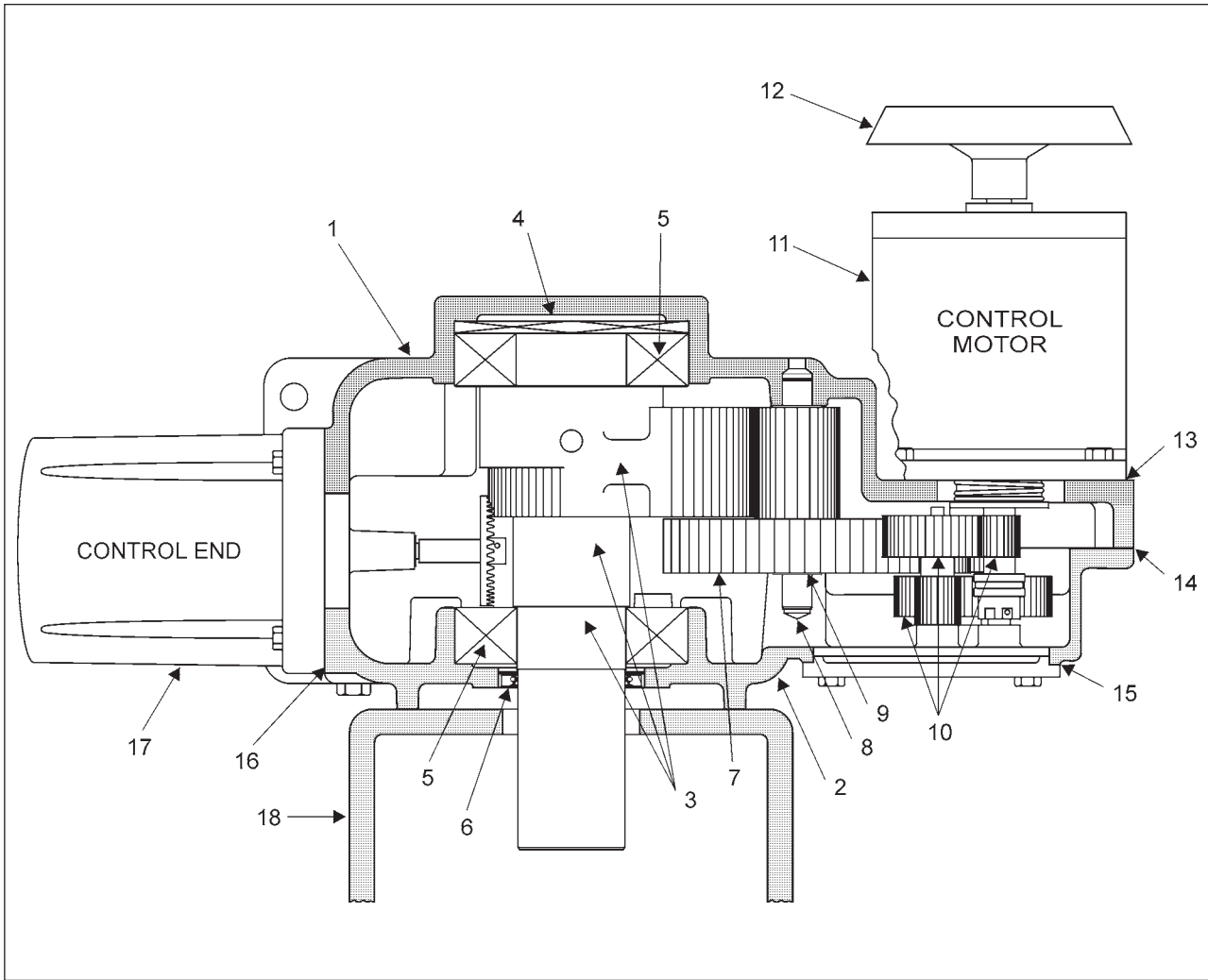
APPENDIX COMPONENTS



**TABLE 9:
DRIVE COMPONENTS FOR MODEL 11-260 / -360**

ITEM NO.	DESCRIPTION	ITEM NO.	DESCRIPTION
1	Body rear	13	Terminal compartment cover
2	Body front	14	ESR compartment cover
3	Output shaft assembly and main gear	15	Gasket, body
4	Spring washer	16	Gasket, gear module
5	Ball bearing, output shaft	17	Gasket, control motor
6	Seal, output shaft	18	Gasket, ESR & terminal cover
7	Gear, 3rd combination	19	Gasket, control end cover
8	Pin, 3rd combination gear	20	Control end cover
9	Thrust washer		Control end cover extension
10	Gear module assembly, see Table 11, page 49, for part number		Terminal block
11	Control motor, see Table 7, page 45, for part number		Barrier, insulator, terminal compartment
12	Handwheel		Barrier plate
			Gasket, barrier plate
			Bracket (11-260 only)

Note: To ensure exact replacement parts, include all nameplate data of the Beck drive with the order.



**TABLE 10:
DRIVE COMPONENTS FOR MODEL 11-460**

ITEM NO.	DESCRIPTION	ITEM NO.	DESCRIPTION
1	Body rear	12	Handwheel
2	Body front	13	Gasket, control motor
3	Output shaft assembly and main gear	14	Gasket, body
4	Spring washer	15	Gasket, gear module
5	Ball bearing, output shaft	16	Gasket, control end cover
6	Seal, output shaft	17	Control end cover
7	Gear, 3rd combination		Control end cover extension
8	Pin, 3rd combination gear		Terminal block
9	Thrust washer		Barrier plate
10	Gear module assembly, see Table 11, page 49, for part number		Gasket, barrier plate
11	Control motor, see Table 7, page 45, for part number		ESR & terminal compartment cover
			Gasket, ESR & terminal cover
			Barrier, insulator, terminal compartment
		18	Bracket

Note: To ensure exact replacement parts, include all nameplate data of the Beck drive with the order.

APPENDIX COMPONENTS

**TABLE 11:
GEARS, TORQUE AND TIMING OPTIONS**

Drive Model Number	Approx. Weight	Maximum Overhung Load	Motor Part Number	Motor Current @ 120 V ac, 60 Hz*	Gear Module Number	Torque	Timing (sec/90°) @ 60 Hz**
11-16_	56 lbs (25 kgs)	750 lbs (340 kgs)	20-2700-20	.17	14-9733-01	80 lb-ft (108 N·m)	81
					14-9733-02	60 lb-ft (81 N·m)	54
					14-9733-03	40 lb-ft (54 N·m)	36
					14-9733-04	20 lb-ft (27 N·m)	18
			20-2701-20	.32	14-9733-03	80 lb-ft (108 N·m)	36
					14-9733-04	40 lb-ft (54 N·m)	18
				14-9733-05	15 lb-ft (20 N·m)	10	
11-26_	115 lbs (52 kgs)	3,000 lbs (1 361 kgs)	20-2704-21	.35	14-9730-04	125 lb-ft (169 N·m)	36
					14-9730-05	175 lb-ft (237 N·m)	54
					14-9730-08	250 lb-ft (339 N·m)	68
			20-2705-21	.56	14-9730-02	125 lb-ft (169 N·m)	18
14-9730-04	250 lb-ft (339 N·m)	36					
11-36_	115 lbs (52 kgs)	4,500 lbs (2 041 kgs)	20-2704-21	.35	14-9730-09	300 lb-ft (407 N·m)	90
			20-2705-21	.56	14-9730-04	300 lb-ft (407 N·m)	36
					14-9730-05	400 lb-ft (542 N·m)	54
					14-9730-08	550 lb-ft (746 N·m)	68
					14-9730-09	650 lb-ft (881 N·m)	90
			11-46_	216 lbs (98 kgs)	9,000 lbs (4 082 kgs)	20-2201-31 Replaces 20-2201-21***	1.25
14-9732-03	1,500 lb-ft (2 034 N·m)	90					
14-9732-04	1,000 lb-ft (1 356 N·m)	68					
14-9732-05	350 lb-ft (475 N·m)	22					
14-9732-07	550 lb-ft (746 N·m)	36					
20-2201-32 Replaces 20-2201-22***	2.20	14-9732-02				1,800 lb-ft (2 440 N·m)	54
		14-9732-05				650 lb-ft (881 N·m)	22
		14-9732-07				1,000 lb-ft (1 356 N·m)	36
20-2201-33 Replaces 20-2201-23***	3.00	14-9732-02				1,800 lb-ft (2 440 N·m)	32
		14-9732-07	1,000 lb-ft (1 356 N·m)	22			

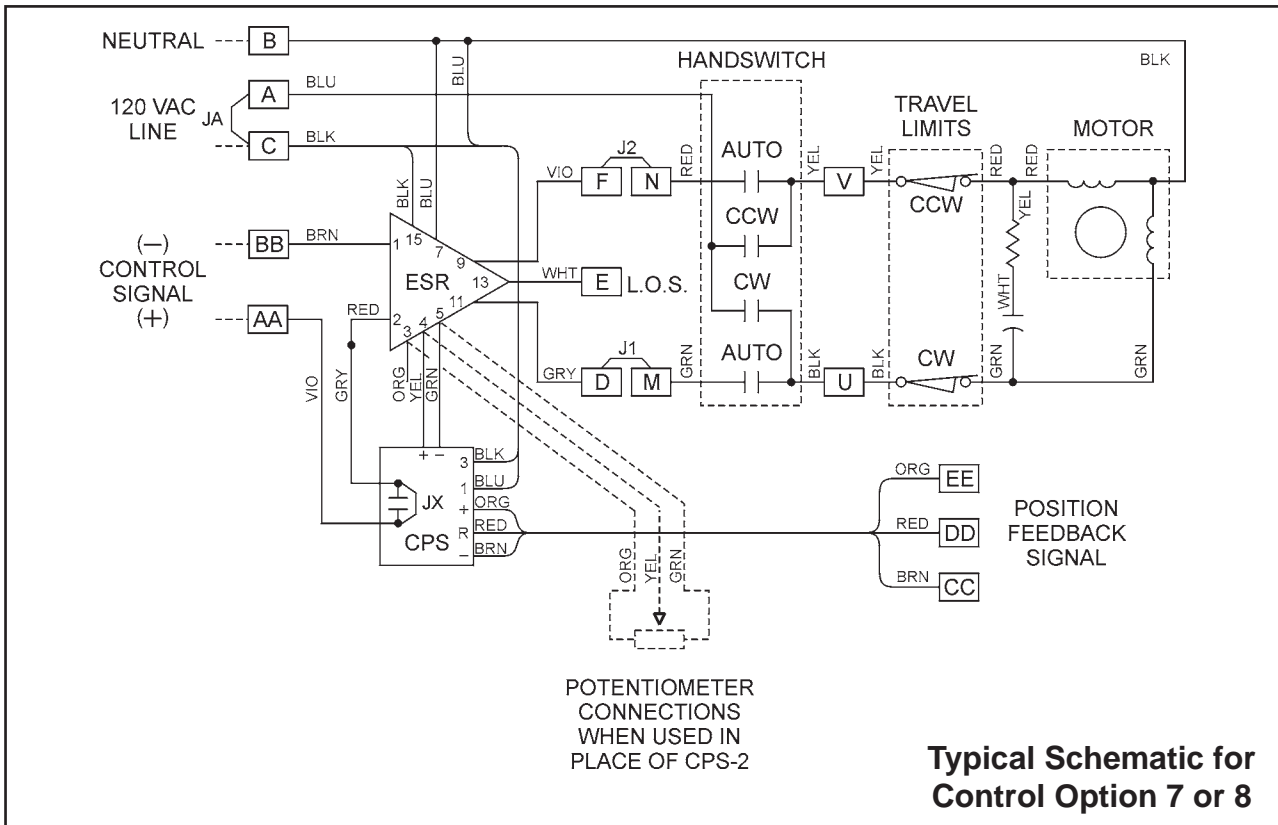
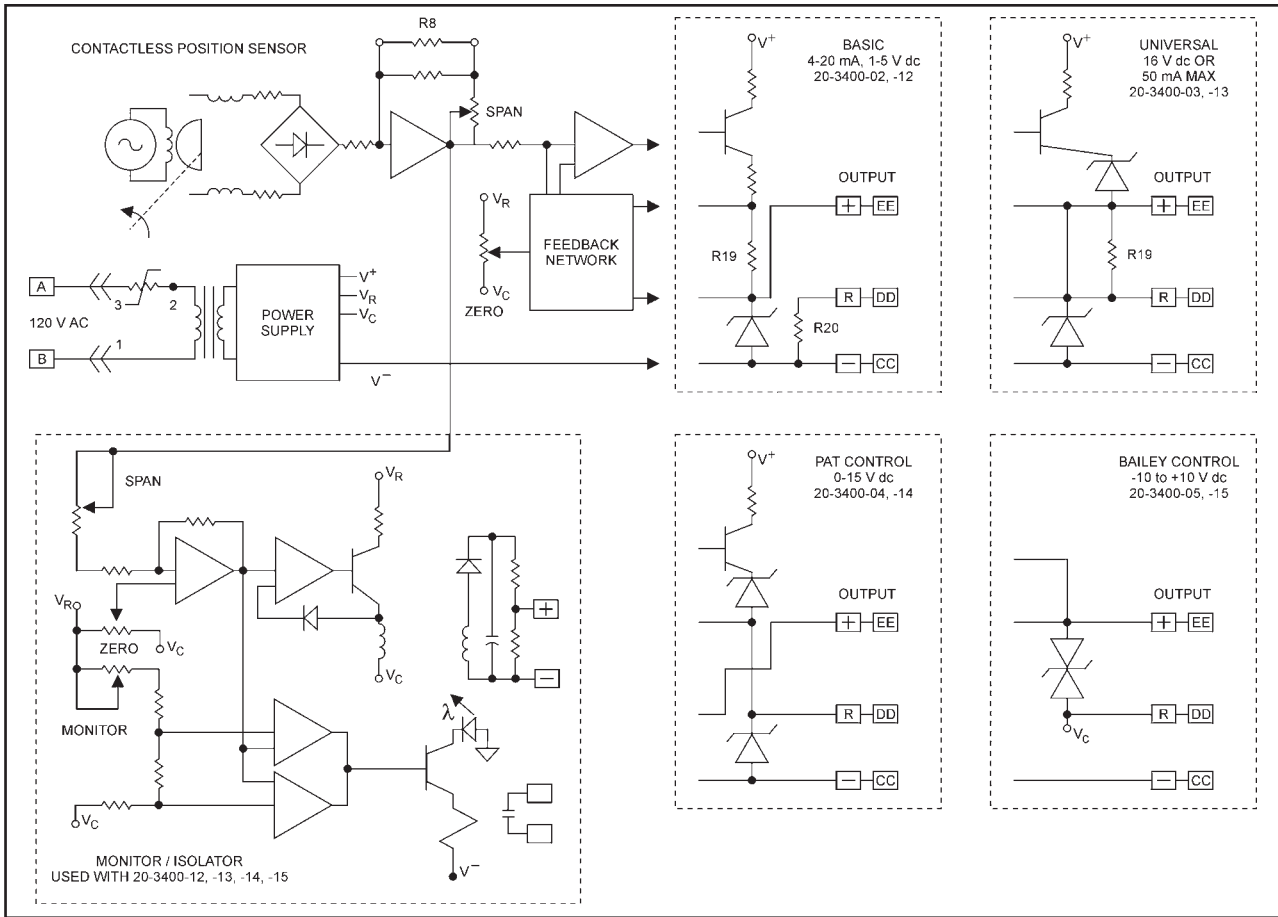
CAUTION: Use only the motor and gear housing combinations listed above; other combinations may cause internal damage to the drive and/or damage to external equipment.

* 50 Hz motor currents do not exceed 110% of 60 Hz levels.

** 50 Hz timing = 1.2 x 60 Hz timing.

*** Obsolete motor.

APPENDIX *CPS-2 FUNCTIONAL BLOCK DIAGRAMS*



APPENDIX *CPS-2 DATA*

**TABLE 12:
CPS-2 SYSTEM APPLICATION DATA SUMMARY**

FEEDBACK SIGNAL OPTIONS	CPS-2 MODEL NO.	EXTERNAL LOAD RESISTANCE	COMPATIBLE CONTROL SYSTEMS
CURRENT 4 TO 20 mA	20-3400-02 & -12 20-3400-03 & -13*	800Ω (Max.) 500Ω (Max.)	Industry Std (ISA)
10 TO 50 mA 1 TO 5 mA	20-3400-03 & -13* 20-3400-03 & -13*	200Ω (Max.) 2KΩ (Max.)	Foxboro General Use
VOLTAGE 1 TO 5 V DC	20-3400-02 & -12 20-3400-03 & -13*	12KΩ (Min.) 250Ω (Min.)	Industry Std (ISA) Beck Position-All (27-301, -401, -501)
0 TO 5 V DC 0 TO 10 V DC 0 TO 16 V DC 0 TO 15 V DC -10 TO 10 V DC	20-3400-03 & -13* 20-3400-03 & -13* 20-3400-03 & -13* 20-3400-04 & -14 20-3400-05 & -15	250Ω (Min.) 1KΩ (Min.) 1KΩ (Min.) 6KΩ (Min.) 2KΩ (Min.)	Leeds and Northrup Bailey, Foxboro, & Westinghouse Leeds and Northrup Leeds and Northrup Bailey

*The 20-3400-03 and -13 may be connected for signal ranges so noted. See Wiring Diagrams on pages 14-15 for details.

**TABLE 13:
CPS-2 SIGNAL OUTPUT TERMINAL CONNECTIONS AND LOADING**

SIGNAL RANGE	OUTPUT TERMINALS (+) (-)	RANGING RESISTOR		RESISTOR CONNECTIONS	MAXIMUM EXTERNAL LOAD
		VALUE	BECK PART NO.		
Model 20-3400-02 & -12 4 to 20 mA 4 to 20 mA 1 to 5 V dc One or Two 1 to 5 V dc Signals	EE - CC EE - DD DD - CC DD - CC EE - DD	Open Open Open 255 Ω Open	 13-2511-03	 DD - EE	800Ω 500Ω 400 μA 400 μA 400 μA
Model 20-3400-03 & -13 Current Output 0 to 4 mA* 1 to 5 mA 4 to 20 mA 10 to 50 mA Voltage Output 0 to 4 V dc* 0 to 5 V dc* 0 to 10 V dc* 0 to 15 V dc* 1 to 5 V dc 2 to 10 V dc 0 to 16 V dc*	 DD - CC DD - CC DD - CC DD - CC EE - CC EE - CC EE - CC EE - CC EE - CC EE - CC EE - CC	 Open Open 332 Ω 110 Ω Jumper 249 Ω 1.50 KΩ 2.74 KΩ Jumper 1.00 KΩ 3.01 KΩ	 13-2511-06 13-2510-25 13-2511-08 13-2512-02 13-2513-42 13-2512-01 13-2513-26	 DD - EE DD - EE CC - DD CC - DD CC - DD CC - DD CC - DD CC - DD	2 KΩ 2 KΩ 500Ω 200Ω 16 mA 16 mA 16 mA 16 mA 16 mA 16 mA 16 mA
Model 20-3400-04 & -14 0 to 15 V dc 15 to 0 V dc	DD - CC EE - DD	Open Open			2.5 mA 2.5 mA
Model 20-3400-05 & -15 -10 to 10 V dc	EE - DD	Open			5 mA

*If factory set for 4-20 mA, zero potentiometer adjustment is required after installation. See page 31.

NOTES

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NOTES

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SERVICES

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Each of Beck's Sales Engineers has access to a complete set of drive models so that he can demonstrate virtually any of their features at your location. In order to arrange to see a Beck drive in your plant or office, contact Beck's Sales Department.

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Beck Sales Engineers are available to discuss your process control requirements. Often a visit to your location is the best way to gain a thorough understanding of your needs, in order to meet them most accurately and completely.

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By sharing your needs with a Beck Sales Engineer you can take advantage of the best application advice for the type of control you need.

This review will yield a better understanding of the versatility of Beck drives for your installations, as well as complete details on options and accessories to make the process as effective as possible.

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Beck provides specification writing assistance in order to help you specify and order the right drives for your applications. Beck Sales Engineers will work with you to make it easier for you to obtain the proper equipment and give you confidence that no details are overlooked.

HOW TO OBTAIN SERVICE

Factory repair of drives or subassemblies is available for both normal and emergency service. To assure prompt processing, contact the factory to receive a Returned Material Authorization (RMA) number. If a repair estimation is desired, please send the name and phone number of your contact for service authorization. It is helpful to include a description of the work desired with the shipment or, in the event of a problem, the malfunction being experienced.

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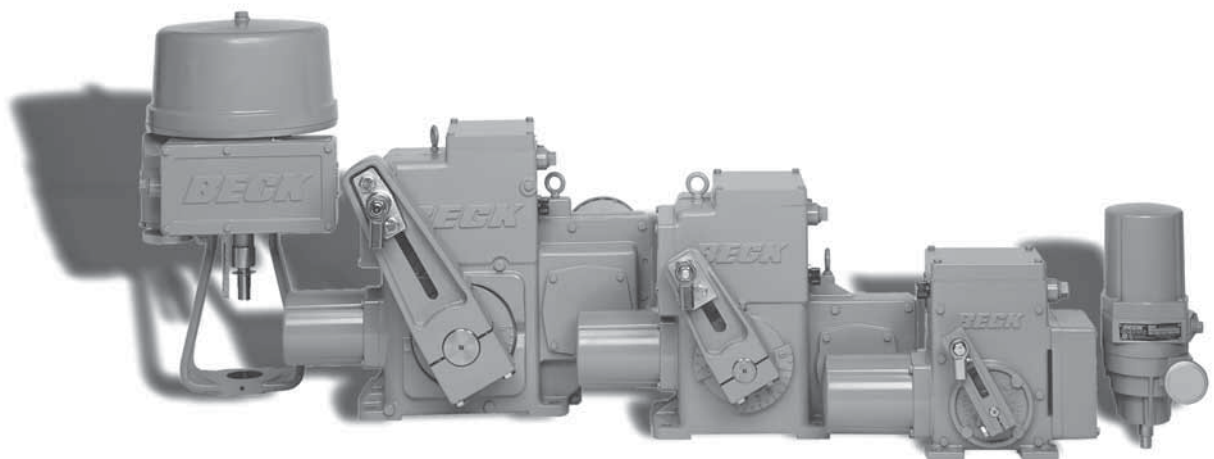
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*Note: Internal water damage is not covered by warranty.

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